Guided Wave Radar

SITRANS LG270 Two-wire 4 ... 20 mA/HART Rod and cable probe -20 ... +250 °C Operating Instructions • 01/2020



SITRANS



Safety Guidelines: Warning notices must be observed to ensure personal safety as well as that of others, and to protect the product and the connected equipment. These warning notices are accompanied by a clarification of the level of caution to be observed.

Qualified Personnel: This device/system may only be set up and operated in conjunction with this manual. Qualified personnel are only authorized to install and operate this equipment in accordance with established safety practices and standards.

Unit Repair and Excluded Liability:

- The user is responsible for all changes and repairs made to the device by the user or the user's
 agent.
- All new components are to be provided by Siemens.
- Restrict repair to faulty components only.
- Do not reuse faulty components.

Warning: Cardboard shipping package provides limited humidity and moisture protection. This product can only function properly and safely if it is correctly transported, stored, installed, set up, operated, and maintained.

This product is intended for use in industrial areas. Operation of this equipment in a residential area may cause interference to several frequency based communications.

Note: Always use product in accordance with specifications.

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|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
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Safety instructions for Ex areas



Take note of the Ex specific safety instructions for Ex applications. These instructions are attached as documents to each instrument with Ex approval and are part of the operating instructions.

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1 About this document

1.1 Function

This instruction provides all the information you need for mounting, connection and setup as well as important instructions for maintenance, fault rectification, the exchange of parts and the safety of the user. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.

1.2 Target group

This operating instructions manual is directed to trained personnel. The contents of this manual must be made available to the qualified personnel and implemented.

1.3 Symbols used

Information, note, tip: This symbol indicates helpful additional information and tips for successful work.

Note: This symbol indicates notes to prevent failures, malfunctions, damage to devices or plants.

Caution: Non-observance of the information marked with this symbol may result in personal injury.

Warning: Non-observance of the information marked with this symbol may result in serious or fatal personal injury.

Danger: Non-observance of the information marked with this symbol results in serious or fatal personal injury.



Ex applications

This symbol indicates special instructions for Ex applications.

List

The dot set in front indicates a list with no implied sequence.

Sequence of actions

Numbers set in front indicate successive steps in a procedure.



1

Battery disposal

This symbol indicates special information about the disposal of batteries and accumulators.

2 For your safety

2.1 Authorised personnel

All operations described in this documentation must be carried out only by trained, qualified personnel authorised by the plant operator.

During work on and with the device, the required personal protective equipment must always be worn.

2.2 Appropriate use

SITRANS LG270 is a sensor for continuous level measurement.

You can find detailed information about the area of application in chapter "*Product description*".

Operational reliability is ensured only if the instrument is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.

2.3 Warning about incorrect use

Inappropriate or incorrect use of this product can give rise to application-specific hazards, e.g. vessel overfill through incorrect mounting or adjustment. Damage to property and persons or environmental contamination can result. Also, the protective characteristics of the instrument can be impaired.

2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and directives. The instrument must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the instrument. When measuring aggressive or corrosive media that can cause a dangerous situation if the instrument malfunctions, the operator has to implement suitable measures to make sure the instrument is functioning properly.

During the entire duration of use, the user is obliged to determine the compliance of the necessary occupational safety measures with the current valid rules and regulations and also take note of new regulations.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden. For safety reasons, only the accessory specified by the manufacturer must be used.

To avoid any danger, the safety approval markings and safety tips on the device must also be observed.

2.5 EU conformity

The device fulfils the legal requirements of the applicable EU directives. By affixing the CE marking, we confirm the conformity of the instrument with these directives.

The EU conformity declaration can be found on our homepage.

Electromagnetic compatibility

Instruments in four-wire or Ex-d-ia version are designed for use in an industrial environment. Nevertheless, electromagnetic interference from electrical conductors and radiated emissions must be taken into account, as is usual with class A instruments according to EN 61326-1. If the instrument is used in a different environment, the electromagnetic compatibility to other instruments must be ensured by suitable measures.

2.6 NAMUR recommendations

NAMUR is the automation technology user association in the process industry in Germany. The published NAMUR recommendations are accepted as the standard in field instrumentation.

The device fulfils the requirements of the following NAMUR recommendations:

- NE 21 Electromagnetic compatibility of equipment
- NE 43 Signal level for fault information from measuring transducers
- NE 53 Compatibility of field devices and display/adjustment components
- NE 107 Self-monitoring and diagnosis of field devices

For further information see www.namur.de.

2.7 Installation and operation in the USA and Canada

This information is only valid for USA and Canada. Hence the following text is only available in the English language.

Installations in the US shall comply with the relevant requirements of the National Electrical Code (ANSI/NFPA 70).

Installations in Canada shall comply with the relevant requirements of the Canadian Electrical Code

A Class 2 power supply unit has to be used for the installation in the USA and Canada.

3 Product description

3.1 Configuration

The scope of delivery encompasses:

- Sensor SITRANS LG270
- Optional accessory

The further scope of delivery encompasses:

- Documentation
 - Operating instructions SITRANS LG270
 - Instructions for optional instrument features
 - Ex-specific "Safety instructions" (with Ex versions)
 - If necessary, further certificates

Information:

Optional instrument features are also described in this operating instructions manual. The respective scope of delivery results from the order specification.

Scope of this operating
instructionsThis operating instructions manual applies to the following instrument
versions:

- Hardware from 1.0.0
- Software from 1.3.0
- Only for instrument versions without SIL qualification

Type label

The type label contains the most important data for identification and use of the instrument:

49915-EN-200212

Scope of delivery

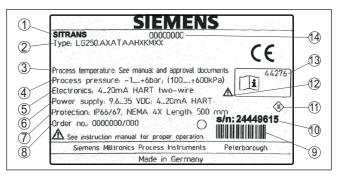


Fig. 1: Layout of the type label (example)

- 1 Instrument type
- 2 Product code
- 3 Process and ambient temperature
- 4 Process pressure
- 5 Signal output electronics
- 6 Voltage supply
- 7 Protection rating
- 8 Order number
- 9 Identification code
- 10 Serial number of the instrument
- 11 Symbol of the device protection class
- 12 Reminder to observe the instrument documentation
- 13 ID numbers, instrument documentation
- 14 Hardware and software version

3.2 Principle of operation

| Application area | The SITRANS LG270 is a level sensor with cable or rod probe for |
|------------------|------------------------------------------------------------------------|
| | continuous level or interface measurement, especially for applications |
| | in high temperatures up to +250° C (482° F). |
| | |

Functional principle level measurement High frequency microwave pulses are guided along a steel cable or a rod. Upon reaching the product surface, the microwave pulses are reflected. The running time is evaluated by the instrument and output as level.

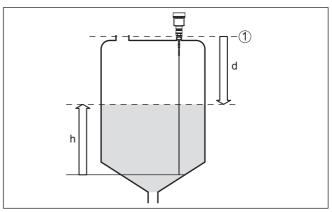


Fig. 2: Level measurement

- 1 Sensor reference plane (seal surface of the process fitting)
- d Distance to the level
- h Height Level

Functional principle - interface measurement

High frequency microwave impulses are guided along a steel cable or rod. Upon reaching the product surface, a part of the microwave impulses is reflected. The other part passes through the upper product and is reflected by the interface. The running times to the two product layers are processed by the instrument.

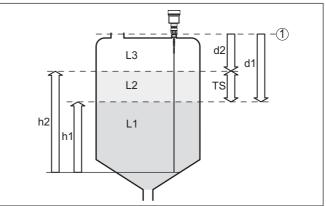


Fig. 3: Interface measurement

- 1 Sensor reference plane (seal surface of the process fitting)
- d1 Distance to the interface
- d2 Distance to the level
- TS Thickness of the upper medium (d1 d2)
- h1 Height Interface
- h2 Height Level
- L1 Lower medium
- L2 Upper medium
- L3 Gas phase

| Output signalThe instrument is always preset to the application "Level measurement". For the interface measurement, you can select the requested outpusignal with the setup.Packaging 3.3 Packaging, transport and storage Your instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a te based on ISO 4180. The packaging consists of environment-friendly, recyclable card- board. For special versions, PE foam or PE foil is also used. Dispos of the packaging material via specialised recycling companies.TransportTransport must be carried out in due consideration of the notes on transport packaging. Nonobservance of these instructions can cau damage to the device.Transport inspectionThe delivery must be checked for completeness and possible trans damage immediately at receipt. Ascertained transit damage or cor cealed defects must be appropriately dealt with. | Prerequisites for inter- face measurement | Upper medium (L2) The upper medium must not be conductive The dielectric constant of the upper medium or the actual distance to the interface must be known (input required). Min. dielectric constant: 1.6. You can find a list of dielectric constants on our home page: www.siemens.com/sitranslg. The composition of the upper medium must be stable, no varying products or mixtures The upper medium must be homogeneous, no stratifications within the medium Min. thickness of the upper medium 50 mm (1.97 in) Clear separation from the lower medium, emulsion phase or detritus layer max. 50 mm (1.97 in) If possible, no foam on the surface Lower medium (L1) The dielectric constant must be 10 higher than the dielectric constant of the upper medium, preferably electrically conductive. Example: upper medium dielectric constant 2, lower medium at least dielectric constant 12. Gas phase (L3) Air or gas mixture Gas phase - dependent on the application, gas phase does not always exist (d2 = 0) |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| signal with the setup. 3.3 Packaging, transport and storagePackagingYour instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a te based on ISO 4180. The packaging consists of environment-friendly, recyclable card- | Output signal | The instrument is always preset to the application "Level measure- ment". |
| PackagingYour instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a te based on ISO 4180. The packaging consists of environment-friendly, recyclable card- | | signal with the setup. |
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| damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.StorageUp to the time of installation, the packages must be left closed and | Transport | Transport must be carried out in due consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device. |
| | Transport inspection | The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or con- cealed defects must be appropriately dealt with. |
| outside. | Storage | |

| | Unless otherwise indicated, the packages must be stored only under the following conditions: Not in the open Dry and dust free Not exposed to corrosive media Protected against solar radiation Avoiding mechanical shock and vibration | |
|--------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| Storage and transport temperature | Storage and transport temperature see chapter "Supplement - Technical data - Ambient conditions" Relative humidity 20 85 % | |
| Lifting and carrying | With instrument weights of more than 18 kg (39.68 lbs) suitable and approved equipment must be used for lifting and carrying. | |
| | 3.4 Accessories | |
| | The instructions for the listed accessories can be found in the down- load area on our homepage. | |
| Display and adjustment module | The display and adjustment module LG Local Display Interface is used for measured value indication, adjustment and diagnosis. | |
| External display and adjustment unit | The LG Remote Interface is an external display and adjustment unit for sensors with single chamber housing and Ex d double chamber housing. | |
| Flanges | Screwed flanges are available in different versions according to the following standards: DIN 2501, EN 1092-1, BS 10, ASME B 16.5, JIS B 2210-1984, GOST 12821-80. | |
| Centering | If you mount the SITRANS LG270 in a bypass tube or standpipe, you have to avoid contact to the bypass tube by using a spacer at the probe end. | |

4 Mounting

4.1 General instructions

Screwing in

On devices with a threaded fitting, the hexagon on the process fitting must be tightened with a suitable wrench.

See chapter "Dimensions" for wrench size.

Warning:

The housing or the electrical connection may not be used for screwing in! Depending on the device version, tightening can cause damage, e. g. to the rotation mechanism of the housing.

Protection against moisture Protect your instrument against moisture ingress through the following measures:

- Use a suitable connection cable (see chapter "Connecting to power supply")
- Tighten the cable gland or plug connector
- Lead the connection cable downward in front of the cable entry or plug connector

This applies mainly to outdoor installations, in areas where high humidity is expected (e.g. through cleaning processes) and on cooled or heated vessels.



Note:

Make sure that the degree of contamination specified in chapter "*Technical data*" meets the existing ambient conditions.



Note:

Make sure that during installation or maintenance no moisture or dirt can get inside the instrument.

To maintain the housing protection, make sure that the housing lid is closed during operation and locked, if necessary.

Cable glands

Metric threads

In the case of instrument housings with metric thread, the cable glands are screwed in at the factory. They are sealed with plastic plugs as transport protection.

You have to remove these plugs before electrical connection.

NPT thread

In the case of instrument housings with self-sealing NPT threads, it is not possible to have the cable entries screwed in at the factory. The free openings for the cable glands are therefore covered with red dust protection caps as transport protection. The dust protection caps do not provide sufficient protection against moisture.

Prior to setup you have to replace these protective caps with approved cable glands or close the openings with suitable blind plugs.

Process conditions



Note:

For safety reasons, the instrument must only be operated within the permissible process conditions. You can find detailed information on

the process conditions in chapter "*Technical data*" of the operating instructions or on the type label.

Hence make sure before mounting that all parts of the instrument exposed to the process are suitable for the existing process conditions.

These are mainly:

- Active measuring component
- Process fitting
- Process seal

Process conditions in particular are:

- Process pressure
- Process temperature
- Chemical properties of the medium
- Abrasion and mechanical influences

4.2 Mounting instructions

Installation position

Mount SITRANS LG270 in such a way that the distance to vessel installations or to the vessel wall is at least 300 mm (12 in). In non-metallic vessels, the distance to the vessel wall should be at least 500 mm (19.7 in).

During operation, the probe must not touch any installations or the vessel wall. If necessary, fasten the probe end.

In vessels with conical bottom it can be advantageous to mount the sensor in the center of the vessel, as measurement is then possible nearly down to the lowest point of the bottom. Keep in mind that measurement all the way down to the tip of the probe may not be possible. The exact value of the min. distance (lower dead zone) is stated in chapter "*Technical data*".

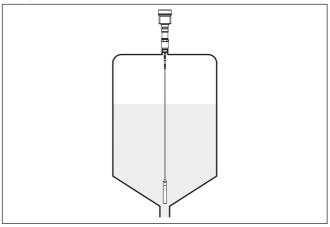


Fig. 4: Vessel with conical bottom

Type of vessel

Plastic vessel/Glass vessel

The guided microwave principle requires a metallic surface on the process fitting. Therefore, in plastic vessels, etc., use an instrument version with flange (from DN 50) or place a metal sheet ($\phi > 200 \text{ mm/8}$ in) beneath the process fitting when screwing it in.

Make sure that the plate has direct contact with the process fitting.

When mounting rod or cable probes in vessels without metal walls, e.g. in plastic vessels, the measured value can be influenced by strong electromagnetic fields (emitted interference according to EN 61326: class A). In this case, use a probe with coaxial version.

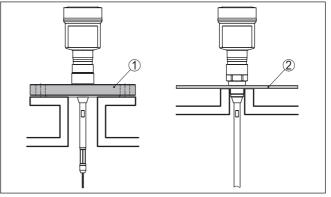


Fig. 5: Mounting in non-metallic vessel

- 1 Flange
- 2 Metal sheet

Mounting socket

If possible, avoid sockets. Mount the sensor flush with the vessel top. If this is not possible, use short sockets with small diameter.

Higher sockets or sockets with a bigger diameter can generally be used. They can, however, increase the upper dead zone. Check if this is relevant for your measurement.

In such cases, always carry out a false signal suppression after mounting. You can find further information under "*Setup procedure*".

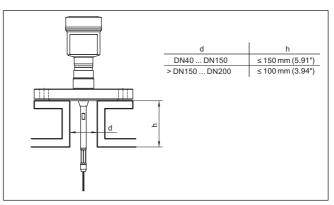


Fig. 6: Mounting socket

When welding the socket, make sure that the socket is flush with the vessel top.

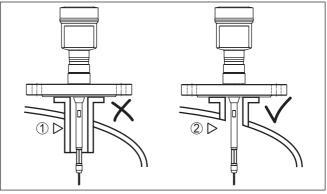


Fig. 7: Socket must be installed flush

- 1 Unfavourable mounting
- 2 Socket flush optimum mounting

Welding work Before beginning the welding work, remove the electronics module from the sensor. By doing this, you avoid damage to the electronics through inductive coupling.

Inflowing medium

Do not mount the instruments in or above the filling stream. Make sure that you detect the product surface, not the inflowing product.

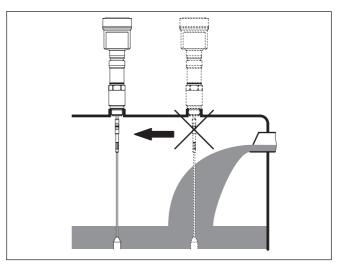


Fig. 8: Mounting of the sensor with inflowing medium

| Measuring range | The reference plane for the measuring range of the sensors is the sealing surface of the thread or flange. |
|-----------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Keep in mind that a min. distance must be maintained below the refer- ence plane and possibly also at the end of the probe - measurement in these areas is not possible (dead zone). The length of the cable can be used all the way to the end only when measuring conductive products. These dead zones for different mediums are listed in chap- ter " <i>Technical data</i> ". Keep in mind for the adjustment that the default setting for the measuring range refers to water. |
| Pressure | The process fitting must be sealed if there is gauge or low pressure in the vessel. Before use, check if the seal material is resistant against the measured product and the process temperature. |
| | The max. permissible pressure is specified in chapter " <i>Technical data</i> " or on the type label of the sensor. |
| Bypass tubes | Standpipes or bypass tubes are normally metal tubes with a diameter of 30 200 mm (1.18 7.87 in). Up to a diameter of 80 mm (3.15 in) such a tube corresponds to a coax measuring probe. Lateral inlets in bypass tubes do not influence the measurement. |
| | Measuring probes can be mounted in bypass tubes up to DN 200. |
| | For bypass tubes, select the probe length such that the dead zone of the probe is above and below the lower lateral filling openings of the bypass tube. You can thus measure the complete range of the medium in the bypass tube (h). When designing the bypass tube, keep the dead zone of the probe in mind and select the length of the bypass tube above the upper lateral filling opening accordingly. |
| | |

Microwaves can penetrate many plastics. This is why plastic tubes are problematic for measurement applications. If durability is no problem, we recommend the use of uncoated metal standpipes.

When the SITRANS LG270 is used in bypass tubes, contact with the tube wall must be avoided. We recommend for this purpose a cable probe with centering weight.



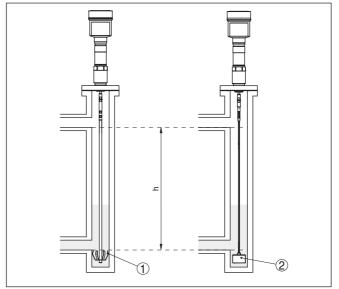
Caution:

When mounting, make sure that the cable is straight over its entire length. A kink in the cable can cause measurement errors and contact with the tube.

With rod probes, a spacer is generally not required. However, if there is a risk of the rod probe being pressed against the tube wall by inflowing medium, you should mount a spacer at the probe end to avoid contact with the tube wall. In the case of cable probes, the cable can be strained.

Keep in mind that the lower dead zone underneath the spacer increases if spacers are used.

Buildup can form on the spacers. Strong buildup can influence the measurement.





- 1 Rod probe with spacer (steel)
- 2 Cable probe with centering weight
- h Measurable tube section



Measurement in a standpipe is not recommended for extremely adhesive products. In case of slight buildup, you should choose a bypass tube with bigger diameter.

49915-EN-200212

Instructions for the measurement:

- The 100 % point in bypass tubes should be below the upper tube connection to the vessel.
- The 0 % point in bypass tubes should be above the lower tube connection to the vessel.
- A false signal suppression with installed sensor is generally recommended to achieve the best possible accuracy.

Standpipes

Standpipes or surge pipes are normally metal tubes with a diameter of 30 ... 200 mm (1.18 ... 7.87 in). Up to a diameter of 80 mm (3.15 in), such a pipe corresponds to a coax measuring probe. It does not matter if the standpipe is perforated or slotted for better mixing.

Measuring probes can be mounted in standpipes up to DN 200.

For standpipes, select the probe length such that the upper dead zone of the probe is above the upper ventilation hole. This allows you to measure the total level range of the medium in the standpipe. When designing the standpipe, keep the upper dead zone of the probe in mind and plan the length above the upper lateral filling opening accordingly.

Microwaves can penetrate many plastics. This is why plastic tubes are problematic for measurement applications. If durability is no problem, we recommend the use of uncoated metal standpipes.

When the SITRANS LG270 is used in standpipes, contact with the tube wall must be avoided. We recommend for this purpose a cable probe with centering weight.



Caution:

When mounting, make sure that the cable is straight over its entire length. A kink in the cable can cause measurement errors and contact with the tube.

With rod probes, a spacer is generally not required. However, if there is a risk of the rod probe being pressed against the tube wall by inflowing medium, you should mount a spacer at the probe end to avoid contact with the tube wall. In the case of cable probes, the cable can be strained.

Keep in mind that the lower dead zone underneath the spacer increases if spacers are used.

Buildup can form on the spacers. Strong buildup can influence the measurement.

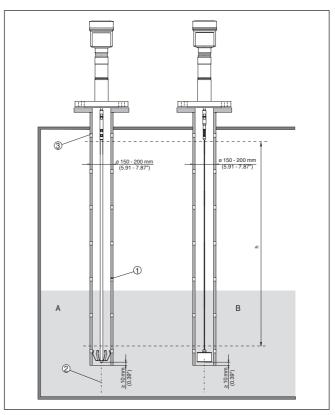


Fig. 10: Mounting in a standpipe

- 1 Holes (for mixing)
- 2 Standpipe vertically mounted max. deviation 10 mm (0.4 in)
- 3 Ventilation opening
- A Rod probe with spacer (steel)
- B Cable probe with centering weight



Note:

Measurement in a standpipe is not recommended for extremely adhesive products. In case of slight buildup, you should choose a standpipe with bigger diameter.

Instructions for the measurement:

- The 100 % point with standpipes should be below the upper ventilation hole.
- The 0 % point in standpipes should be above the gravity or centering weight.
- A false signal suppression with installed sensor is generally recommended to achieve the best possible accuracy.

49915-EN-200212

Mounting in the vessel insulation

Instruments for a temperature range up to +250 °C (482 °F) have a spacer between process fitting and electronics housing. This spacer is used to thermally decouple the electronics from the high process temperatures.

Information: The spacer m

The spacer may be incorporated in the vessel insulation up to max. 50 mm (2 in). Only then is a reliable temperature decoupling guaranteed.

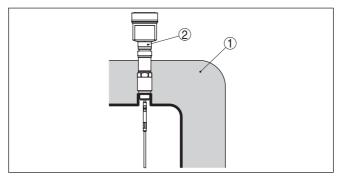


Fig. 11: Mounting the instrument on insulated vessels.

1 Temperature insulation

2 Ambient temperature on the housing

Fasten

If there is a risk of the cable probe touching the vessel wall during operation due to product movements or agitators, etc., the measuring probe should be securely fixed.

There is an internal thread (M8) in the gravity weight, e.g. for an eyebolt (optional).

Make sure that the probe cable is not completely taut. Avoid tensile loads on the cable.

Avoid undefined vessel connections, i.e. the connection must be either grounded reliably or isolated reliably. Any undefined change of this condition can lead to measurement errors.

If there is a danger of the rod probe touching the vessel wall, fasten the probe at the bottom end.

Keep in mind that measurement is not possible below the fastening point.

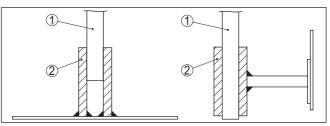


Fig. 12: Fasten the probe

- 1 Measuring probe
- 2 Retaining sleeve

Fixing facility

If there is a risk of the cable probe touching the vessel wall during operation due to product movements or agitators, etc., the measuring probe can be strained.

For this purpose there is an internal thread (M12 or M8) in the gravity weight.

Make sure that the probe cable is only hand tight. Avoid strong tensile loads on the cable.

Keep in mind that measurement is only possible up to the tensioning component. For this reason, order the cable probe 270 mm longer.

L = L1 + 270 mm (10.63 in)

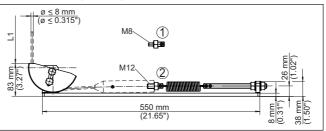


Fig. 13: Tensioning component for cable versions

- 1 Holding screw M8
- 2 Holding screw M12
- L1 Max. measuring length

Probe length L = L1 + 270 mm (10.63 in)

Lateral installation

In case of difficult installation conditions, the probe can also be mounted laterally. For this, adapt the rod with rod extensions or angled segments.

To compensate for the resulting changes in signal runtime, let the instrument determine the probe length automatically.

The determined probe length can deviate from the actual probe length when using curved or angled segments.

If internal installations such as struts, ladders, etc. are present on the vessel wall, the measuring probe should be mounted at least 300 mm (11.81 in) away from the vessel wall.

You can find further information in the supplementary instructions of the rod extension.

5 Connecting to power supply 5.1 Preparing the connection Safety instructions Always keep in mind the following safety instructions: Carry out electrical connection by trained, qualified personnel authorised by the plant operator If overvoltage surges are expected, overvoltage arresters should be installed Warning: Only connect or disconnect in de-energized state. Voltage supply Power supply and current signal are carried on the same two-wire cable. The operating voltage can differ depending on the instrument version. The data for power supply are specified in chapter "Technical data". Provide a reliable separation between the supply circuit and the mains circuits according to DIN EN 61140 VDE 0140-1. Power the instrument via an energy-limited circuit acc. to IEC 61010-1, e.g. via Class 2 power supply unit. Keep in mind the following additional factors that influence the operating voltage: • Lower output voltage of the power supply unit under nominal load (e.g. with a sensor current of 20.5 mA or 22 mA in case of fault) Influence of additional instruments in the circuit (see load values in chapter "Technical data") Connection cable The instrument is connected with standard two-wire cable without screen. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas. screened cable should be used. Use cable with round cross section for instruments with housing and cable gland. Use a cable gland suitable for the cable diameter to ensure the seal effect of the cable gland (IP protection rating). We generally recommend the use of shielded cable for HART multidrop mode. **Cable glands** Metric threads In the case of instrument housings with metric thread, the cable glands are screwed in at the factory. They are sealed with plastic plugs as transport protection. Note: You have to remove these plugs before electrical connection. NPT thread

In the case of instrument housings with self-sealing NPT threads, it is not possible to have the cable entries screwed in at the factory. The free openings for the cable glands are therefore covered with red dust protection caps as transport protection.

| • | Note: |
|---|---------|
| 1 | Prior 1 |

Prior to setup you have to replace these protective caps with approved cable glands or close the openings with suitable blind plugs.

On plastic housings, the NPT cable gland or the Conduit steel tube must be screwed into the threaded insert without grease.

Max. torque for all housings, see chapter "Technical data".

Cable screening and grounding

If screened cable is required, we recommend connecting the cable screening on both ends to ground potential. In the sensor, the cable screening must be connected directly to the internal ground terminal. The ground terminal on the outside of the housing must be connected to the ground potential (low impedance).



In Ex systems, the grounding is carried out according to the installation regulations.

In electroplating plants as well as plants for cathodic corrosion protection it must be taken into account that significant potential differences exist. This can lead to unacceptably high currents in the cable screen if it is grounded at both ends.

Note:

The metallic parts of the instrument (process fitting, sensor, concentric tube, etc.) are connected with the internal and external ground terminal on the housing. This connection exists either directly via the conductive metallic parts or, in case of instruments with external electronics, via the screen of the special connection cable.

You can find specifications on the potential connections inside the instrument in chapter "*Technical data*".

5.2 Connecting

The voltage supply and signal output are connected via the springloaded terminals in the housing.

Connection to the display and adjustment module or to the interface adapter is carried out via contact pins in the housing.

• Information: The terminal b

The terminal block is pluggable and can be removed from the electronics. To do this, lift the terminal block with a small screwdriver and pull it out. When reinserting the terminal block, you should hear it snap in.

Connection procedure

Connection technology

Proceed as follows:

- 1. Unscrew the housing lid
- 2. If a display and adjustment module is installed, remove it by turning it slightly to the left
- 3. Loosen compression nut of the cable gland and remove blind plug
- 4. Remove approx. 10 cm (4 in) of the cable mantle, strip approx. 1 cm (0.4 in) of insulation from the ends of the individual wires
- 5. Insert the cable into the sensor through the cable entry

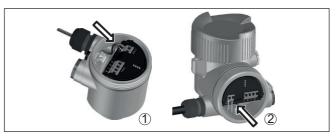


Fig. 14: Connection steps 5 and 6

- 1 Single chamber housing
- 2 Double chamber housing
- 6. Insert the wire ends into the terminals according to the wiring plan

Note:

Solid cores as well as flexible cores with wire end sleeves are inserted directly into the terminal openings. In case of flexible cores without end sleeves, press the terminal from above with a small screwdriver, the terminal opening is then free. When the screwdriver is released, the terminal closes again.

- 7. Check the hold of the wires in the terminals by lightly pulling on them
- 8. Connect the screen to the internal ground terminal, connect the external ground terminal to potential equalisation
- 9. Tighten the compression nut of the cable entry gland. The seal ring must completely encircle the cable
- 10. Reinsert the display and adjustment module, if one was installed
- 11. Screw the housing lid back on

The electrical connection is finished.

5.3 Wiring plan, single chamber housing



The following illustration applies to the non-Ex, Ex-ia and Ex-d version.

Electronics and connection compartment

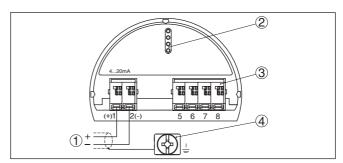
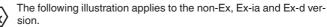


Fig. 15: Electronics and connection compartment - single chamber housing

- 1 Voltage supply, signal output
- 2 For display and adjustment module or interface adapter
- 3 For external display and adjustment unit
- 4 Ground terminal for connection of the cable screening

5.4 Wiring plan, double chamber housing



Electronics compartment

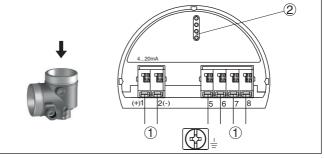


Fig. 16: Electronics compartment - double chamber housing

- 1 Internal connection to the connection compartment
- 2 For display and adjustment module or interface adapter

Connection compartment

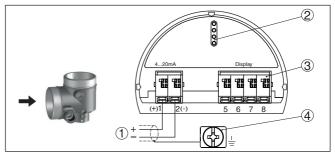


Fig. 17: Connection compartment - double chamber housing

- 1 Voltage supply, signal output
- 2 For display and adjustment module or interface adapter
- 3 For external display and adjustment unit
- 4 Ground terminal for connection of the cable screening

5.5 Wiring plan, Ex-d-ia double chamber housing

Electronics compartment

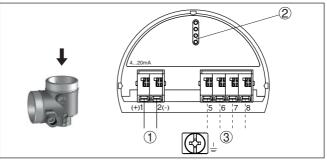


Fig. 18: Electronics compartment - Ex-d-ia double chamber housing

- 1 Internal connection to the connection compartment
- 2 For display and adjustment module or interface adapter
- 3 Internal connection to the plug connector for external display and adjustment unit (optional)

Note:

HART multidrop mode is not possible when using an Ex-d-ia instrument.

Connection compartment

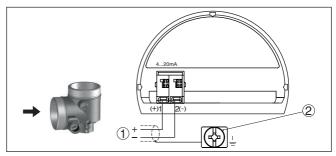


Fig. 19: Connection compartment - Ex-d-ia double chamber housing

- 1 Voltage supply, signal output
- 2 Ground terminal for connection of the cable screening

5.6 Supplementary electronics

Supplementary electronics - Additional current output

To make a second measured value available for use, you can use the supplementary electronics "Additional current output".

Both current outputs are passive and need a power supply.

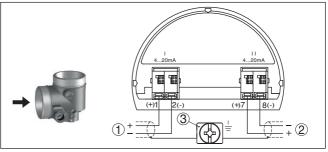


Fig. 20: Terminal compartment, double chamber housing, supplementary electronics "Additional current output"

- 1 First current output (I) Voltage supply and signal output, sensor (HART)
- 2 Additional current output (II) Voltage supply and signal output (without HART)
- 3 Ground terminal for connection of the cable screening

5.7 Switch-on phase

After connection of the device to power supply, the device first carries out a self-test:

- Internal check of the electronics
- Indication of the status message "F 105 Determine measured value" on the display or PC
- The output signal jumps briefly to the set fault current

Then the actual measured value is output to the signal cable. The value takes into account settings that have already been carried out, e.g. default setting.

6 Set up with the display and adjustment module

6.1 Insert display and adjustment module

The display and adjustment module can be inserted into the sensor and removed again at any time. You can choose any one of four different positions - each displaced by 90°. It is not necessary to interrupt the power supply.

Proceed as follows:

- 1. Unscrew the housing lid
- 2. Place the display and adjustment module on the electronics in the desired position and turn it to the right until it snaps in.
- 3. Screw housing lid with inspection window tightly back on

Disassembly is carried out in reverse order.

The display and adjustment module is powered by the sensor, an additional connection is not necessary.



Fig. 21: Installing the display and adjustment module in the electronics compartment of the single chamber housing



Fig. 22: Installing the display and adjustment module in the double chamber housing

- 1 In the electronics compartment
- 2 In the connection compartment

Note:

Т.

If you intend to retrofit the instrument with a display and adjustment module for continuous measured value indication, a higher lid with an inspection glass is required.

6.2 Adjustment system

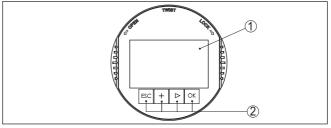


Fig. 23: Display and adjustment elements

- 1 LC display
- 2 Adjustment keys

Key functions

- [OK] key:
 - Move to the menu overview
 - Confirm selected menu
 - Edit parameter
 - Save value
- *[->]* key:
 - Change measured value presentation
 - Select list entry
 - Select editing position
- [+] key:
 - Change value of the parameter
- *[ESC]* key:
 - Interrupt input
 - Jump to next higher menu

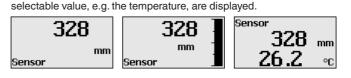
Adjustment system The sensor is operated via the four keys of the display and adjustment module. The individual menu items are shown on the LC display. You can find the function of the individual keys in the previous illustration.

When the [+] and [->] keys are pressed quickly, the edited value, or the cursor, changes one value or position at a time. If the key is pressed longer than 1 s, the value or position changes continuously.

When the *[OK]* and *[ESC]* keys are pressed simultaneously for more than 5 s, the display returns to the main menu. The menu language is then switched over to "*English*".

Approx. 60 minutes after the last pressing of a key, an automatic reset to measured value indication is triggered. Any values not confirmed with *[OK]* will not be saved.

| Switch-on phase | After switching on, the SITRANS LG270 carries out a short self-test where the device software is checked. | | |
|--------------------------------|--------------------------------------------------------------------------------------------------------------------------------|--|--|
| | The output signal transmits a fault signal during the switch-on phase. | | |
| | The following information is displayed on the display and adjustment module during the startup procedure: | | |
| | Instrument type Device name Software version (SW-Ver) Hardware version (HW-Ver) | | |
| Measured value indica- tion | With the [->] key you can move between three different indication modes. | | |
| | In the first view, the selected measured value is displayed in large digits. | | |
| | In the second view, the selected measured value and a correspond- ing bar graph presentation are displayed. | | |
| | In the third view, the selected measured value as well as a second | | |



6.3 Parameter adjustment - Quick setup

To quickly and easily adapt the sensor to the application, select the menu item "*Quick setup*" in the start graphic on the display and adjustment module.



The following steps for the quick setup can be reached also in the "Extended adjustment".

- Instrument address
- Measurement loop name
- Medium type (optional)
- Application
- Max. adjustment
- Min. adjustment
- False signal suppression

You can find the description of the individual menu items in the following chapter "Parameter adjustment - Extended adjustment".

6.4 Parameter adjustment - Extended adjustment

For technically demanding measuring points, you can carry out extended settings in "Extended adjustment".

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Quick setup



Main menu

The main menu is divided into five sections with the following functions:



Setup: Settings, e.g. measurement loop name, medium, vessel, adjustment, signal output, device unit, false signal suppression, linearization curve

Display: Settings, e.g., for language, measured value display, lighting

Diagnosis: Information, e.g. on instrument status, pointer, measurement reliability, simulation, echo curve

Additional adjustments: Reset, date/time, reset, copy function

Info: Instrument name, hardware and software version, date of manufacture, instrument features



Note:

For optimum adjustment of the measuring point, the individual submenu items in the main menu item "Setup" should be selected one after the other and provided with the correct parameters. If possible, go through the items in the given sequence.

The procedure is described below.

The following submenu points are available:





The submenu points are described below.

6.4.1 Setup

Measurement loop name

Here you can assign a suitable measurement loop name. Push the "OK" key to start the editing. With the "+" key you change the sign and with the "->" key you jump to the next position.

You can enter names with max, 19 characters. The character set comprises:

- Capital letters from A ... Z
- Numbers from 0 ... 9
- Special characters + / blanks

Measurement loop name

TANK 04

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Units

In this menu item you select the distance unit and the temperature unit.

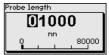
| Distance unit | |
|------------------|----------|
| mm | • |
| Tenperature unit | |
| °C | • |
| | |

For the distance units you can choose between m, mm and ft and for the temperature units $^{\circ}C$, $^{\circ}F$ and K.

 Probe length
 In this menu item you can enter the probe length or have the length determined automatically by the sensor system.

When choosing "*Yes*", then the probe length will be determined automatically. When choosing "*No*", you can enter the probe length manually.





Application - Medium
typeCoax probes can be only used in liquids. In this menu item, the fixed
adjusted medium type "Liquid" is displayed.



Application - Application

In this menu item, you can select the application. You can choose between level measurement and interface measurement. You can also choose between measurement in a vessel or in a bypass or standpipe.

• Note: The se

The selection of the application has a considerable influence on all other menu items. Keep in mind that as you continue with the parameter adjustment, individual menu items are only optionally available.

You have the option of choosing the demonstration mode. This mode is only suitable for test and demonstration purposes. In this mode, the sensor ignores the parameters of the application and reacts immediately to any change.



Application / Level vessel Level bypass/standpipe Interface vessel Interf.bypass/standpipe Denonstration node

Application - Medium, dielectric constant

In this menu item, you can define the type of medium (product).

This menu item is only available if you have selected level measurement under the menu item "*Application*".

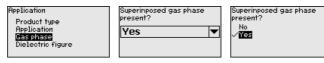
| Application | Mediun/Dielectric constant | Mediun/Dielectric constant |
|---------------------------------------------------------|----------------------------|--------------------------------------------------------------|
| Product type Application Medium/Dielectric figure | Water-based/>10 🔻 | Solvents,oilLPG/<3 Chen. nixtures/310 /Water=based/>10 |

You can choose between the following medium types:

| Dielectric con- stant | Type of medium | Examples |
|--------------------------|--------------------------|---------------------------------------------------------------|
| > 10 | Water-based liq- uids | Acids, alcalis, water |
| 3 10 | Chemical mix- tures | Chlorobenzene, nitro lacquer, aniline, isocyanate, chloroform |
| < 3 | Hydrocarbons | Solvents, oils, liquid gas |

Application - Gas phase This menu item is only available, if you have chosen interface measurement under the menu item "*Application*". In this menu item you can enter if there is a superimposed gas phase in your application.

> Only set the function to "Yes", if the gas phase is permanently present.



Application - Dielectric constant

This menu item is only available if you have selected interface measurement under the menu item "*Application*". In this menu item you can enter the dielectric constant of the upper medium.



You can directly enter the dielectric constant of the upper medium or have the value determined by the instrument.

If you want the dielectric constant to be determined by the instrument, you have to enter the measured or known distance to the interface.

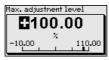


Max. adjustment level

In this menu item you can enter the max. adjustment for the level. With interface measurement this is the maximum total level.



Adjust the requested percentage value with [+] and store with [OK].



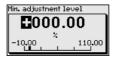
Enter the appropriate distance value in m (corresponding to the percentage value) for the full vessel. The distance refers to the sensor reference plane (seal surface of the process fitting). Keep in mind that the max. level must lie below the dead zone.



Min. adjustment level In this menu item you can enter the min. adjustment for the level. With interface measurement this is the minimum total level.



Adjust the requested percentage value with [+] and store with [OK].



Enter the suitable distance value in m for the empty vessel (e.g. distance from the flange to the probe end) corresponding to the percentage value. The distance refers to the sensor reference plane (seal surface of the process fitting).



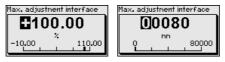
Max. adjustment interface This menu item is only available if you have selected interface measurement under the menu item "*Application*".



Enter the requested percentage value for the max. adjustment.

As an alternative, you have the possibility taking over the adjustment of the level measurement also for the interface.

Enter the respective distance value in m for the surface of the upper medium corresponding to the percentage value.



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Min. adjustment interface

This menu item is only available if you have selected interface measurement under the menu item "Application".



Enter the requested percentage value for the min. adjustment (interface).

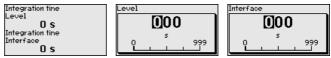
Enter the respective distance value in m for the interface corresponding to the percentage value of the interface.



Damping

To damp process-dependent measured value fluctuations, set an integration time of 0 \dots 999 s in this menu item.

If you have selected interface measurement under the menu item "*Application*", you can adjust the damping for the level and the interface separately.

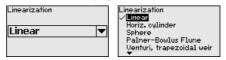


The default setting is a damping of 0 s.

Linearisation

A linearisation is necessary for all vessels in which the vessel volume does not increase linearly with the level - e.g. a horizontal cylindrical or spherical tank, when the indication or output of the volume is required. Corresponding linearisation curves are preprogrammed for these vessels. They represent the correlation between the level percentage and vessel volume.

The linearisation applies to the measured value indication and the current output. By activating the appropriate curve, the volume percentage of the vessel is displayed correctly. If the volume should not be displayed in percent but e.g. in I or kg, a scaling can be also set in the menu item "*Display*".





Warning:

If a linearisation curve is selected, the measuring signal is no longer necessarily linear to the filling height. This must be considered by the user especially when setting the switching point on the limit signal transmitter.

In the following, you have to enter the values for your vessel, for example the vessel height and the socket correction.

For non-linear vessel forms, enter the vessel height and the socket correction.

For the vessel height, you have to enter the total height of the vessel.

For the socket correction you have to enter the height of the socket above the upper edge of the vessel. If the socket is lower than the upper edge of the vessel, this value can also be negative.

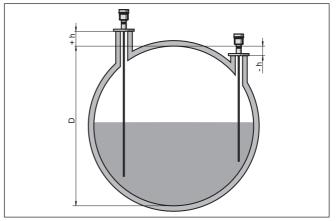
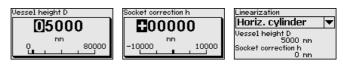


Fig. 24: Vessel height and socket correction value

- D Vessel height
- +h Positive socket correction value
- -h Negative socket correction value



Current output mode In the menu item "*Current output mode*" you determine the output characteristics and reaction of the current output in case of fault.

| Current output node Output characteristics | Output characteristics | Failu |
|-----------------------------------------------|-----------------------------------|---------------------|
| 4 20 mA 💌 | √ <mark>4 20 mA</mark> 20 4 mA | ✓ <u>K=</u> >= ; |
| Failure mode < 3.6 mA ▼ | | Las |
| < 3.6 mA 🛛 🔻 | | |

Failure node ✓**K=3:6 mB** >= 21 mR Last value

The default setting is output characteristics 4 \dots 20 mA, fault mode < 3.6 mA.

Current output, min./max.

In the menu item "Current output Min./Max.", you determine the reaction of the current output during operation.







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The default setting is min. current 3.8 mA and max. current 20.5 mA.

False signal suppression

The following circumstances cause interfering reflections and can influence the measurement:

- High mounting sockets
- Vessel internals such as struts

Note:

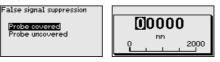
A false signal suppression detects, marks and saves these false signals so that they are no longer taken into account for the level and interface measurement. We generally recommend carrying out a false signal suppression to achieve the best possible accuracy. This should be done with the lowest possible level so that all potential interfering reflections can be detected.

Proceed as follows:



Select first if the probe is covered or uncovered.

If the probe is covered, enter the actual distance from the sensor to the product surface.



All interfering signals in this section are detected by the sensor and stored.

Keep in mind that with covered probe only false signals in the uncovered area of the probe are detected.

Note:

Check the distance to the product surface, because if an incorrect (too large) value is entered, the existing level will be saved as a false signal. The level would then no longer be detectable in this area.

If a false signal suppression has already been created in the sensor, the following menu window appears when selecting "*False signal suppression*":



The instrument carries out an automatic false signal suppression as soon as the probe is uncovered. The false signal suppression is always updated.

The menu item "*Delete*" is used to completely delete an already created false signal suppression. This is useful if the saved false signal suppression no longer matches the metrological conditions in the vessel.

Lock/Unlock adjustment

In the menu item "*Lock/unlock adjustment*", you can protect the sensor parameters against unauthorized or inadvertent modification. The PIN is activated/deactivated permanently.

With active PIN, only the following adjustment functions are possible without entering a PIN:

- Select menu items and show data
- Read data from the sensor into the display and adjustment module





Caution:

When the PIN is active, adjustment via PACTware/DTM as well as other systems is also blocked.

In delivery status, the PIN is 0000.

Call our service department if you have modified and forgotten the PIN.

Current output 2 If a supplementary electronics with an additional current output is installed in the instrument, you can adjust the additional current output separately.

In menu item"*Current output 2*" you specify which measured value the additional current output refers to.

The procedure corresponds to the previous settings of the standard current output. See "*Setup - Current output*".

6.4.2 Display

In the main menu point "*Display*", the individual submenu points should be selected one after the other and provided with the correct parameters to ensure the optimum adjustment of the display options. The procedure is described in the following.

The following submenu points are available:

| Display |
|--------------------|
| Menu language |
| Indication value 1 |
| Indication value 2 |
| Display format |
| Backlight |

The submenu points are described below.

Menu language

Display

This menu item enables the setting of the requested national language.

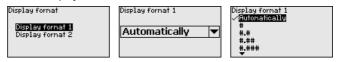
| Menu language English | Menu language Deutsch ✓ Englisi Français Español |
|-----------------------|---------------------------------------------------------------------|
| | Pycokuu ▼ |

In delivery status, the sensor is set to English.

Displayed value 1 In this menu item, you define the indication of the measured value on the display. You can display two different measured values. In this menu item, you define measured value 1. Indication value 1 Displayed value Percent, level Lin.percent, level Percent, level -Filling height, level Distance, level Scaled level The default setting for the displayed value 1 is "Filling height Level". **Displayed value 2** In this menu item, you define the indication of the measured value on the display. You can display two different measured values. In this menu item, you define measured value 2. Displayed value 2 Displayed value 2 Scaled level Meas. reliability, level Electronics temperature V Electronics temperature Dielectric constan Current The default setting for the displayed value 2 is the electronics temperature.

Display format In this menu item, you define the display format of the measured value on the display. You can define different display formats for the two measured values.

You can thus define the number of decimal positions the measured value is displayed with.



The default setting for the display format is "Automatic".

Backlight The integrated background lighting can be switched off via the adjustment menu. The function depends on the strength of the supply voltage, see "Technical data".

To maintain the function of the device, the lighting is temporarily switched off if the power supply is insufficient.

| Backlight | |
|-------------|-------------|
| Switched on | Switch off? |

In delivery status, the lighting is switched on.

6.4.3 Diagnostics

Sensor status

In this menu item, the device status is displayed.

When the instrument displays a failure message, you can here get detailed information on the failure reason.

Diagnostics Device status Peak values Distance Peak indicator, reliab. Peak values further Echo curve

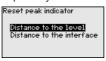


Peak values, distance The respective min. and max. measured value is saved in the sensor. The two values are displayed in the menu item "*Peak values, distance*".

If you have selected interface measurement under the menu item "Setup - Application", the peak values of the interface measurement are displayed in addition to the peak values of the level measurement.

| Diagnostics Device status Peak values Distance Peak values further Echo avera | Distance to the level Min. 68 mr Max. 265 mr Distance to the interface Min. 132 mr | า |
|-------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------|---|
| Echo curve | Min. 132 mr Max. 322 mr | |

In another window you can carry out a reset of the two peak values separately.



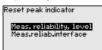
Peak values, measurement reliability The respective min. and max. measured values are saved in the sensor. The two values are displayed in the menu item "*Peak values, measurement reliability*".

The measurement can be influenced by the process conditions. In this menu item, the measurement reliability of the level measurement is displayed in mV. The higher the value, the more reliable the measurement.

If you have selected interface measurement under the menu item "*Setup - Application*", the peak values of the interface measurement are displayed in addition to the peak values of the level measurement.

| Diagnostics | Meas.reliability, level |
|-------------------------|------------------------------|
| Device status | Min. 1 mV |
| Peak values Distance | Max. 279 mV |
| Peak indicator, reliab. | Meas, reliability, interface |
| Peak values further | Min. 1 mV |
| Echo curve | Max. 316 mV |
| • | |

In another window you can carry out a reset of the two peak values separately.



Peak values, additional

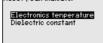
The respective min. and max. measured values are saved in the sensor. The values are displayed in the menu item "*Peak values Ad-ditional*".

This menu item displays the peak values of the electronics temperature as well as the dielectric constant.

| Peak values Distance Peak indicator, reliab. | Electronic Min. Max. Dielectric Min. Max. | s temperature 27.28 °C 28.84 °C constant 1.00 1.00 |
|-------------------------------------------------|----------------------------------------------------------|-------------------------------------------------------------------|
|-------------------------------------------------|----------------------------------------------------------|-------------------------------------------------------------------|

In another window you can carry out a reset of the two peak values separately.

| Pacat | po pk | indicato | , |
|-------|-------|----------|---|

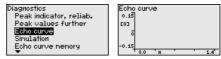


Information:

If one of the display values flashes, there is actually no valid value available.

Echo curve

The menu item "*Echo curve*" shows the signal strength of the echoes over the measuring range in V. The signal strength enables an evaluation of the quality of the measurement.



With the following functions you can zoom part sections of the echo curve.

- "X-Zoom": Zoom function for the meas. distance
- "Y-Zoom": 1, 2, 5 and 10x signal magnification in "V"
- "Unzoom": Reset the presentation to the nominal measuring range without magnification



Simulation

In this menu item you can simulate measured values via the current output. This allows the signal path to be tested, e.g. through downstream indicating instruments or the input card of the control system.



Select the requested simulation variable and set the requested value.



| Simulation running |
|--------------------|
| Percent |
| 79.4 % |





Caution:

During simulation, the simulated value is output as 4 ... 20 mA current value and digital HART signal.

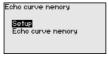
Push the [ESC] key to deactivate the simulation.

Information:

The simulation is terminated automatically 60 minutes after the activation of the simulation.

Echo curve memory With the menu item "*Setup*" the echo curve it is possible to save at the time of setup. This is generally recommended; for using the Asset Management functions it is necessary. If possible, the curve should be saved with a low level in the vessel.

With this, you can detect signal changes over the operating time. With the adjustment software PACTware and the PC, the high-resolution echo curve can be displayed and used to compare the echo curve of the setup with the actual echo curve.



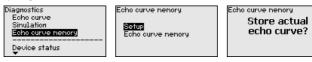
Echo curve nenory Save echo curve of the setup?

The function "*Echo curve memory*" enables storing echo curves of the measurement.

Under the sub-menu item "*Echo curve memory*" you can store the current echo curve.

Parameter settings for recording the echo curve and the settings of the echo curve itself can be carried out in the adjustment software PACTware.

With the adjustment software PACTware and the PC the high-resolution echo curve can be displayed and used later on to assess the quality of the measurement.



6.4.4 Additional adjustments

In this menu item, the internal clock of the sensor is set.

Date/Time

Date∕Tine 9:28 3. Mar 2016 Change now?

Format ✓<mark>24 h</mark> 12 h





Reset

After a reset, certain parameter adjustments made by the user are reset.

Note:

After this menu window, the reset process is carried out. No further safety inquiry follows.

| Reset |
|------------------|
| |
| |
| Factory settings |
| Basic settings |
| Dable Sernings |
| |
| |
| |

The following reset functions are available:

Delivery status: Restores the parameter settings at the time of shipment from the factory, incl. order-specific settings. Any stored false signal suppression or user-programmed linearisation curve, as well as the measured value memory, are deleted.

Basic settings: Restores the parameter settings, incl. special parameters, to the default values of the respective instrument. Any stored false signal suppression or user-programmed linearisation curve, as well as the measured value memory, are deleted.

The following table shows the default values of the instrument. Depending on the instrument version or application, all menu items may not be available or some may be differently assigned:

| Menu item | Default value |
|----------------------------------------|------------------------------------------|
| Lock adjustment | Released |
| Measurement loop name | Sensor |
| Units | Distance unit: order-specific |
| | Temperature unit: order-specific |
| Probe length | Länge der Messsonde factory setting |
| Type of medium | Liquid |
| Application | Level, vessel |
| Medium, dielectric constant | Water-based, > 10 |
| Superimposed gas phase | Yes |
| Dielectric constant, upper medium (TS) | 1.5 |
| Tube inner diameter | 200 mm |
| Max. adjustment - Level | 100 % |
| | Distance: 0.000 m(d) - Note dead zones |
| Min. adjustment - Level | 0 % |
| | Distance: Probe length - Note dead zones |
| Max. adjustment - Interface | 100 % |
| | Distance: 0.000 m(d) - Note dead zones |
| Min. adjustment - Interface | 0 % |
| | Distance: Probe length - Note dead zones |
| Damping - Level | 0.0 s |
| Damping - Interface | 0.0 s |

Menu - Setup

| Menu item | Default value |
|----------------------------------------------|-------------------------------|
| | |
| Linearisation type | Linear |
| Linearisation - Socket correction | 0 mm |
| Linearisation - Vessel height | Probe length |
| Scaling variable - Level | Volume in I |
| Scaling unit - Level | Litres |
| Scaling format - Level | Without decimal positions |
| Scaling level - 100 % corresponds to | 100 |
| Scaling level - 0 % corresponds to | 0 |
| Scaling variable - Interface | Volume |
| Scaling unit - Interface | Litres |
| Scaling format - Interface | Without decimal positions |
| Scaling interface - 100 % corresponds to | 100 |
| Scaling interface - 0 % corresponds to | 0 |
| Current output, output variable | Lin. percent - Level |
| Current output - Output characteristics | 0 100 % correspond to 4 20 mA |
| Current output - Reaction in case of fault | ≤ 3.6 mA |
| Current output - Min. | 3.8 mA |
| Current output - Max. | 20.5 mA |
| Current output 2 - Output variable | Distance - Level |
| Current output 2 - Output characteristics | 0 100 % correspond to 4 20 mA |
| Current output 2 - Reaction in case of fault | ≤ 3.6 mA |
| Current output 2 - Min. | 3.8 mA |
| Current output 2 - Max. | 20.5 mA |

Menu - Display

| Menu item | Default value |
|-------------------|-------------------------|
| Language | Selected language |
| Displayed value 1 | Filling height |
| Displayed value 2 | Electronics temperature |
| Display format 1 | Automatically |
| Display format 2 | Automatically |
| Backlight | Switched on |

Menu - Additional adjustments

| Menu item | Default value |
|-----------|---------------|
| PIN | 0000 |
| Date | Actual date |

| Menu item | Default value |
|---------------|-----------------|
| Time | Actual time |
| Time - Format | 24 hours |
| Probe type | Device-specific |

Copy instrument settings

The instrument settings are copied with this function. The following functions are available:

- Read from sensor: Read data from sensor and store into the display and adjustment module
- Write into sensor: Store data from the display and adjustment module back into the sensor

The following data or settings for adjustment of the display and adjustment module are saved:

- All data of the menu "Setup" and "Display"
- In the menu "Additional adjustments" the items "Reset, Date/Time"
- Special parameters



Prerequisites

The following requirements must be met for a successful transmission:

- The data can only be transferred to the same device type, e.g. SITRANS LG270
- It must be the same probe type, e.g. rod probe
- The firmware of both devices is identical

The copied data are permanently saved in an EEPROM memory in the display and adjustment module and remain there even in case of power failure. From there, they can be written into one or more sensors or kept as backup for a possible electronics exchange.

Note:

Before the data are stored in the sensor, a check is carried out to determine if the data fit the sensor. If the data do not fit, a fault signal is triggered or the function is blocked. When data are being written into the sensor, the display shows which instrument type the data originate from and which TAG-no. this sensor had.

Tip:

We recommend to save the instrument adjustments. In case of an electronics exchange the saved parameter adjustment data relieve this process.

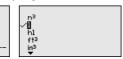
Since scaling is very extensive, scaling of the level value was divided into two menu items.

| Scaling level | |
|------------------|--|
| | |
| | |
| Scaling variable | |
| Scaling format | |
| ordaning ronnar | |
| | |
| | |
| | |

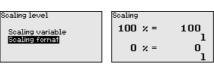
Scaling level - Scaling prime

In menu item "Scaling variable" you define the scaling variable and the scaling unit for the level value on the display, e.g. volume in I.

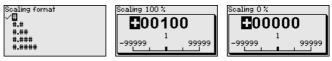




Scaling level - Scaling format



In menu item "Scaling format" you define the scaling format on the display and the scaling of the measured level value for 0 % and 100 %.



Scaling interface

Since scaling is very extensive, scaling of the interface value was divided into two menu items.

Scaling interface



Scaling interface - Scaling size

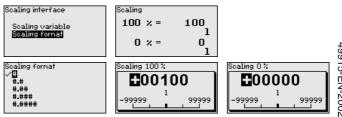
In menu item "Scaling variable" you define the scaling variable and the scaling unit for the interface value on the display, e.g. volume in I.

> m³ 1 h1 f†3

| Scaling variable Volume I | Mass Flow Volume Others |
|---------------------------|----------------------------------|
|---------------------------|----------------------------------|

Scaling interface - Scaling format

In menu item "Scaling format" you define the scaling format on the display and the scaling of the measured interface value for 0 % and 100 %.



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Current output

Since scaling is very extensive, scaling of the level value was divided into two menu items.

| Current output |
|----------------------------|
| Current output variable |
| Current output, adjustment |
| |
| |

Current output - Current output size

In menu item "*Current output, variable*" you specify which measured variable the current output refers to.

| Current output variable Lin.percent, level | Current output variable Distance, level Percent, level Chippercent, level Scaled level Filling height, level |
|-----------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------|
| | Tilling Height, level |

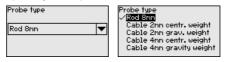
Current output - Current output adjustment

In menu item "*Current output, adjustment*" you can assign a respective measured value to the current output.

| Current output, adjustment | Current output 100 % | Current output 0 % |
|----------------------------|----------------------|----------------------|
| 100 × = 100.00 °C | 00000 | 0 0100 |
| 0.00 = × 0 °C | -99999 1 99999 | -99999 <u>999</u> 99 |

Probe type

In this menu item you can select the type and size of your probe from a list of all possible probes. This is necessary to adapt the electronics optimally to the probe.



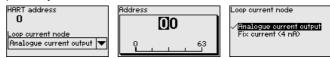
HART mode

The sensor offers the HART modes "*Analogue current output*" and "*Fix current (4 mA)*". In this menu item you determine the HART mode and enter the address with Multidrop mode.

In the mode "*Fixed current output*" up to 63 sensors can be operated on one two-wire cable (Multidrop operation). An address between 0 and 63 must be assigned to each sensor.

If you select the function "*Analogue current output*" and also enter an address number, you can output a 4 ... 20 mA signal in Multidrop mode.

In the mode "*Fixed current (4 mA)*" a fixed 4 mA signal is output independently of the actual level.



The default setting is "Analogue current output" and the address 00.

In this menu item you gain access to the protected area where you can enter special parameters. In exceptional cases, individual

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Special parameters

parameters can be modified in order to adapt the sensor to special requirements.

Change the settings of the special parameters only after having contacted our service staff.

| Service login | |
|---------------|--|
| 10A | |
| | |

6.4.5 Info

Device name

In this menu, you read out the instrument name and the instrument serial number.

Instrument version

In this menu item, the hardware and software version of the sensor is displayed.



Factory calibration date In this menu item, the date of factory calibration of the sensor as well as the date of the last change of sensor parameters are displayed via the display and adjustment module or via the PC.

| Factory calibration date | |
|--------------------------|------|
| 3. Aug 2012 | |
| Last change | LUIL |
| 29. Nov | 2012 |
| 2311101 | |

Sensor characteristics In this menu item, the features of the sensor such as approval, process fitting, seal, measuring range, electronics, housing and others are displayed.

| Sensor characteristics | Sensor characteristics Process fitting ∕ | Sensor characteristics Cable entry / Conn |
|------------------------|-------------------------------------------------|----------------------------------------------|
| Display now? | Material Thread G& PN6, DIN 3852-A / 316L | ection M20x1.5 / Cable gl and PA black |
| | | |

Example for displayed sensor features.

6.5 Saving the parameterisation data

On paper We recommended writing down the adjustment data, e.g. in this operating instructions manual, and archiving them afterwards. They are thus available for multiple use or service purposes.

In the display and adjustment module If the instrument is equipped with a display and adjustment module, the parameter adjustment data can be saved therein. The procedure is described in menu item "*Copy device settings*".

7 Setup with PACTware

7.1 Connect the PC

Via the interface adapter directly on the sensor



Fig. 25: Connection of the PC directly to the sensor via the interface adapter

- 1 USB cable to the PC
- 2 Interface adapter
- 3 Sensor

Connection via HART

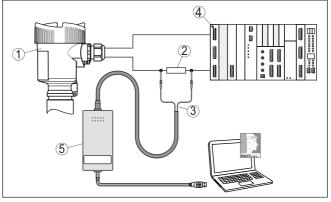


Fig. 26: Connecting the PC via HART to the signal cable

- 1 Sensor
- 2 HART resistance 250 Ω (optional depending on evaluation)
- 3 Adapter cable for HART modem
- 4 Processing system/PLC/Voltage supply
- 5 HART modem



For power supply units with integrated HART resistance (inner resistance approx. 250Ω), there is no additional external resistance necessary. Standard Ex separators are often provided with a sufficiently high current limitation resistance. In such cases, the modem can be connected in parallel to the 4 ... 20 mA cable.

7.2 Parameter adjustment with PACTware

Prerequisites

For parameter adjustment of the sensor via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The available DTMs are compiled on a DVD. The DTMs can also be integrated into other frame applications according to FDT standard.

Note:

To ensure that all instrument functions are supported, you should always use the latest DTM Collection. Furthermore, not all described functions are included in older firmware versions. You can download the latest instrument software from our homepage. A description of the update procedure is also available in the Internet.

The further setup steps are described in the online help of PACTware and the DTMs.

| Sensor # Parametrierung | | 4 10 |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------|
| Device name: Description: Measurement loop nam | SITRANS LG TDR sensor for continuous level measurement with 4 _ 20 ne: Sensor | mA/HART interface SIEMENS |
| Image: Setup Setup Probe length Application Application Type of linearization Scling, level Current output Current torbarcteristic HART variables False signal suppression | Adjustment, level (Set distances for Max, adjustment Min, adjustment | level percentages) Sensor reference plane Distance A Distance B |
| Display Diagnostics Additional settings Info Measured values | Max. adjustment in % Distance A Min. adjustment in % | 100,00 % |
| Software version 1.1.0/PRE05 Serial number 90000008 Device status OK | Distance B | 1000 mm |
| Filling height of the level • 657 mm | Distance to level | 343 mm |
| R constant and R Population | | OK Cancel Apply |

Fig. 27: Example of a DTM view

Device DTMs The device DTM includes an assistant for simple project configuration simplifying also the adjustment considerably. You can save and print your project documentation as well as import and export projects.

You can also save measured value and echo curves in the DTM. Furthermore a tank calculation program as well as a multiviewer for indication and analysis of the saved measured value and echo curves are available.

The supplied DVD includes the respective device DTM. However, you can also download the DTM from our homepage www.siemens.com/sitranslg.

7.3 Set up with the quick setup

General information

The quick setup is another option for parameter adjustment of the sensor. It allows fast, convenient adjustment of the most important parameters to adapt the sensor quickly to standard applications. To use it, select the function "*Quick setup*" in the start screen.

| Sensor # Setup and maintenance | | | 4 ⊳ × |
|--------------------------------------------------------|-------------|---------------------------------------------------------------------------------------------------|-------------------|
| | | | |
| Device name: Description: Measurement loop name: | | is level measurement with 4 $_$ 20 mA/HART interface | SIEMENS |
| Setup and maintenance | | | |
| | | Quick setup | ard applications. |
| - | - | This function is only available with connected sen | sor (online). |
| | | Parameter adjustment of all sensor functions. This also an offline parameter adjustment. | function enables |
| | | Maintenance | |
| | | Assistants for diagnosis and service. These function available with connected sensor (online). | ins are only |
| SI | TRANS LG | | |
| | | | |
| | | | |
| Connected 🛛 😵 Device and da | ita set 🛛 🗐 | Administrator | |

Fig. 28: Select quick setup

- 1 Quick setup
- 2 Extended adjustment
- 3 Maintenance

Quick setup

With quick setup you can carry out the parameter adjustment of SITRANS LG270 for your application in just a few simple steps. The assistant-driven adjustment includes the basic settings for simple, reliable setup and commissioning.

Information:

If the function is inactive, then possibly no instrument is connected. Check the connection to the instrument.

Extended adjustment

With the extended adjustment, you carry out the parameter adjustment for the instrument via the clear menu structure in the DTM (Device Type Manager). This enables additional and special settings over and above those offered by quick setup.

Maintenance

Under the menu item "*Maintenance*" you get comprehensive and important support for servicing and maintenance. You can call up diagnostic functions and carry out an electronics exchange or a software update.

Start quick setup

Click to the button "*Quick setup*", to start the assistant-driven adjustment for a simplified and reliable setup.

7.4 Saving the parameterisation data

We recommend documenting or saving the parameterisation data via PACTware. That way the data are available for multiple use or service purposes.

8 Set up with other systems

8.1 DD adjustment programs

Device descriptions as Enhanced Device Description (EDD) are available for DD adjustment programs such as, for example, AMS \uparrow and PDM.

8.2 Field Communicator 375, 475

Device descriptions for the instrument are available as EDD for parameterisation with Field Communicator 375 or 475.

Integrating the EDD into the Field Communicator 375 or 475 requires the "Easy Upgrade Utility" software, which is available from the manufacturer. This software is updated via the Internet and new EDDs are automatically accepted into the device catalogue of this software after they are released by the manufacturer. They can then be transferred to a Field Communicator.

9 Diagnostics and servicing

| | 9.1 Maintenance |
|-----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Maintenance | If the device is used properly, no special maintenance is required in normal operation. |
| Cleaning | The cleaning helps that the type label and markings on the instrument are visible. |
| | Take note of the following: |
| | • Use only cleaning agents which do not corrode the housings, type label and seals |
| | Use only cleaning methods corresponding to the housing protec- tion rating |
| | 9.2 Diagnosis memory |
| | The instrument has several memories available for diagnostic pur- poses. The data remain there even in case of voltage interruption. |
| Measured value memory | Up to 100,000 measured values can be stored in the sensor in a ring memory. Each entry contains date/time as well as the respective measured value. Storable values are for example: |
| | Distance Filling height Percentage value Lin. percent Scaled Current value |
| | Measurement reliabilityElectronics temperature |
| | When the instrument is shipped, the measured value memory is active and stores distance, measurement reliability and electronics temperature every 3 minutes. |
| | In "Extended adjustment" you can select the respective measured values. |
| | The requested values and recording conditions are set via a PC with PACTware/DTM or the control system with EDD. Data are thus read out and also reset. |
| Event memory | Up to 500 events are automatically stored with a time stamp in the sensor (non-deletable). Each entry contains date/time, event type, event description and value. Event types are for example: |
| | Modification of a parameter Switch-on and switch-off times Status messages (according to NE 107) Error messages (according to NE 107) |
| | The data are read out via a PC with PACTware/DTM or the control system with EDD. |

Echo curve memory The echo curves are stored with date and time and the corresponding echo data. The memory is divided into two sections:

Echo curve of the setup: This is used as reference echo curve for the measurement conditions during setup. Changes in the measurement conditions during operation or buildup on the sensor can thus be recognized. The echo curve of the setup is stored via:

- PC with PACTware/DTM
- Control system with EDD
- Display and adjustment module

Further echo curves: Up to 10 echo curves can be stored in a ring buffer in this memory section. Additional echo curves are stored via:

- PC with PACTware/DTM
- Control system with EDD
- Display and adjustment module

9.3 Status messages

The instrument features self-monitoring and diagnostics according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables there are more detailed error messages available under the menu item "*Diagnostics*" via the respective adjustment module.

Status messages

The status messages are divided into the following categories:

- Failure
- Function check
- Out of specification
- Maintenance requirement

and explained by pictographs:

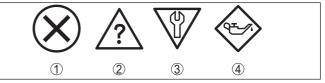


Fig. 29: Pictographs of the status messages

- 1 Failure red
- 2 Out of specification yellow
- 3 Function check orange
- 4 Maintenance blue

Failure: Due to a malfunction in the instrument, a fault message is output.

This status message is always active. It cannot be deactivated by the user.

Function check: The instrument is being worked on, the measured value is temporarily invalid (for example during simulation).

This status message is inactive by default.

Out of specification: The measured value is unreliable because an instrument specification was exceeded (e.g. electronics temperature).

This status message is inactive by default.

Maintenance: Due to external influences, the instrument function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the instrument because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default.

| Code | Cause | Rectification | DevSpec State in CMD 48 |
|------------------------------|----------------------------------------------------------------------------------------|--------------------------------------------------------------------------------|-------------------------|
| Text mes- sage | | | |
| F013 no measured | Sensor does not detect an echo during operation | Check for correct mounting and/or parameter settings | Bit 0 of Byte 0 5 |
| value avail- able | Process component or probe contaminated or defective | Clean or exchange process component or probe | |
| F017 | Adjustment not within speci- | Change adjustment according | Bit 1 of Byte 0 5 |
| Adjustment span too small | fication | to the limit values (differ- ence between min. and max. ≥ 10 mm) | |
| F025 Error in the | Index markers are not con- tinuously rising, for example | Check values of the lineariza- tion table | Bit 2 of Byte 0 5 |
| linearization table | illogical value pairs | Delete/create a new lineariza- tion table | |
| F036 | Failed or interrupted software | Repeat software update | Bit 3 of Byte 0 5 |
| No operable | update | Check electronics version | |
| software | | Exchanging the electronics | |
| | | Send instrument for repair | |
| F040 | Hardware defect | Exchanging the electronics | Bit 4 of Byte 0 5 |
| Error in the electronics | | Send instrument for repair | |
| F041 | Probe mechanically defective | Check probe and exchange, if | Bit 13 of Byte 0 5 |
| Probe loss | | necessary | |
| F080 | General software error | Disconnect operating voltage | Bit 5 of Byte 0 5 |
| General soft- ware error | | briefly | |
| F105 | The instrument is still in the | Wait for the end of the switch- | Bit 6 of Byte 0 5 |
| Measured value is deter- | start phase, the measured val- ue could not yet be determined | on phase | |
| mined | | Duration depending on the ver- sion and parameter adjustment max. 5 min. | |
| F113 | EMC interference | Remove EMC influences | Bit 12 of Byte 0 5 |
| Communica- tion error | Transmission error during ex- ternal communication with 4-wire power supply unit | Exchange 4-wire power supply unit or electronics | |

Failure

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| Code | Cause | Rectification | DevSpec State in CMD 48 |
|------------------------------------------------|------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------|---------------------------|
| Text mes- sage | | | |
| F260 Error in the calibration | Error in the calibration carried out in the factory Error in the EEPROM | Exchanging the electronics Send instrument for repair | Bit 8 of Byte 0 5 |
| F261 Error in the instrument settings | Error during setup Error when carrying out a reset False signal suppression faulty | Carry out a reset Repeat setup | Bit 9 of Byte 0 … 5 |
| F264 Installation/ Setup error | Error during setup | Check for correct mounting and/or parameter settings Check probe length | Bit 10 of Byte 0 5 |
| F265 Measurement function dis- turbed | Sensor no longer carries out a measurement | Carry out a reset Disconnect operating voltage briefly | Bit 11 of Byte 0 5 |
| F267 No executable sensor soft- ware | Sensor cannot start | Exchanging the electronics Send instrument for repair | No communication possible |

Tab. 5: Error codes and text messages, information on causes as well as corrective measures (some specifications are only valid for four-wire instruments)

Function check

| Code Text mes- sage | Cause | Rectification | DevSpec State in CMD 48 |
|--------------------------------|------------------------|---------------------------------------------------------------------|-----------------------------------------------------|
| C700 Simulation ac- tive | A simulation is active | Finish simulation Wait for the automatic end af- ter 60 mins. | "Simulation Active" in "Stand- ardized Status 0" |

Tab. 6: Error codes and text messages, information on causes as well as corrective measures

Out of specification

| Code | Cause | Rectification | DevSpec |
|------------------------------|--------------------------------------|--------------------------------------------------------|-----------------|
| Text message | | | State in CMD 48 |
| S600 | Temperature of the processing elec- | Check ambient temperature | Bit 8 of |
| Impermissible | tronics in the non-specified section | Insulate electronics | Byte 14 24 |
| electronics tem- perature | | Use instrument with higher temper- ature range | |
| S601 | Level echo in the close range not | Reduce level | Bit 9 of |
| Overfilling | available | 100 % adjustment: Increase value | Byte 14 24 |
| | | Check mounting socket | |
| | | Remove possible interfering signals in the close range | |
| | | Use coaxial probe | |

| Code Text message | Cause | Rectification | DevSpec State in CMD 48 |
|-------------------------------------------------------------------|---------------------------------------------|----------------------------------------------------------------------------|----------------------------|
| S602 Level within the search range, compensation echo | Compensation echo superimposed by medium | 100 % adjustment: Increase value | Bit 10 of Byte 14 … 24 |
| S603 Impermissible operating voltage | Operating voltage below specified range | Check electrical connection If necessary, increase operating voltage | Bit 11 of Byte 14 24 |

Tab. 7: Error codes and text messages, information on causes as well as corrective measures

Maintenance

| Code | Cause | Rectification | DevSpec |
|--------------------------------------------------|-----------------------------------------------------------|--------------------------------------------------------|------------------------|
| Text message | | | State in CMD 48 |
| M500 | The data could not be restored dur- | Repeat reset | Bit 0 of |
| Error in the deliv- ery status | ing the reset to delivery status | Load XML file with sensor data into the sensor | Byte 14 24 |
| M501 | Index markers are not continuous- | Check linearisation table | Bit 1 of |
| Error in the non-active line- arisation table | ly rising, for example illogical value pairs | Delete table/Create new | Byte 14 24 |
| M504 | Hardware defect | Exchanging the electronics | Bit 4 of |
| Error at a device interface | | Send instrument for repair | Byte 14 24 |
| M505 no measured val- | Sensor does not detect an echo dur- ing operation | Check and correct mounting and/or parameter adjustment | Bit 5 of Byte 14 24 |
| ue available | Process component or probe con- taminated or defective | Clean or exchange process compo- nent or probe | |
| M506 | Error during setup | Check and correct mounting and/or | Bit 6 of |
| Installation/Set- | | parameter adjustment | Byte 14 24 |
| up error | | Check probe length | |
| M507 | Error during setup | Carry out reset and repeat setup | Bit 7 of |
| Error in the in- | Error when carrying out a reset | | Byte 14 24 |
| strument settings | False signal suppression faulty | | |

Tab. 8: Error codes and text messages, information on causes as well as corrective measures

Rectify faults 9.4

Reaction when malfunc-The operator of the system is responsible for taking suitable meastion occurs ures to rectify faults.

Fault rectification

The first measures are:

- Evaluation of fault messages
- Checking the output signal
- Treatment of measurement errors .

Further comprehensive diagnostics options are available with a PC/ notebook with PACTware and the suitable DTM. In many cases, the reasons can be determined in this way and faults rectified.

4 ... 20 mA signal Connect a multimeter in the suitable measuring range according to the wiring plan. The following table describes possible errors in the current signal and helps to eliminate them:

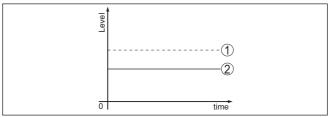
| Error | Cause | Rectification |
|-----------------------------------------------------|----------------------------------------------------------|-----------------------------------------------------------------------|
| 4 20 mA signal not stable | Fluctuating measured value | Set damping |
| 4 20 mA signal missing | Electrical connection faulty | Check connection, correct, if necessary |
| | Voltage supply missing | Check cables for breaks; repair if nec- essary |
| | Operating voltage too low, load resist- ance too high | Check, adapt if necessary |
| Current signal greater than 22 mA, less than 3.6 mA | Sensor electronics defective | Replace device or send in for repair de- pending on device version |

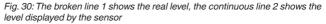
Treatment of measurement errors

The below tables show typical examples for application-relevant measurement errors. There are two measurement errors:

- Constant level
- Filling
- Emptying

The images in column "*Error pattern*" show the real level as a broken line and the level displayed by the sensor as a continuous line.





Note:

If the output level is constant, the cause could also be the fault setting of the current output to "*Hold value*".

If the level is too low, the reason could be a line resistance that is too high

Measurement error with constant level

| Fault description | Cause | Rectification |
|-----------------------------------------|----------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------|
| Measured value shows a | Min./max. adjustment not correct | Adapt min./max. adjustment |
| too low or too high level | Incorrect linearisation curve | Adapt linearisation curve |
| δ δ δ | Running time error (small measurement error close to 100 %/serious error close to 0 %) | Repeat setup |
| Measured value jumps to- wards 100 % | Due to the process, the amplitude of the product echo decreases | Carry out a false signal suppression |
| [Powel | A false signal suppression was not car- ried out | |
| 01 5me | Amplitude or position of a false signal has changed (e.g. buildup); false signal suppression no longer matches | Determine the reason for the changed false signals, carry out false signal sup- pression, e.g. with buildup |

Measurement error during filling

| Fault description | Cause | Rectification |
|----------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------|
| Measured value remains in the area of the bottom dur- ing filling | Echo from the probe end larger than the product echo, for example, with products with ϵ_r < 2.5 oil-based, solvents, etc. | Check parameter "Medium" and "Vessel height", adapt if necessary |
| Measured value remains momentarily unchanged during filling and then jumps to the correct level | Turbulence on the product surface, quick filling | Check parameters, change if necessary, e.g. in dosing vessel, reactor |
| Measured value jumps sporadically to 100 % dur- ing filling | Changing condensation or contamina- tion on the probe | Carry out a false signal suppression |
| Measured value jumps to ≥ 100 % or 0 m distance | Level echo is no longer detected in the close range due to false signals in the close range. The sensor goes into over- fill protection mode. The max. level (0 m distance) as well as the status message "Overfill protection" are output. | Eliminate false signals in the close range Check installation conditions If possible, switch off the function "Over- fill protection" |

Measurement error during emptying

| Fault description | Cause | Rectification |
|---------------------------------------------------------------------------|----------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Measured value remains unchanged in the close range during emptying | False signal larger than the level echo Level echo too small | Eliminate false signals in the close range Remove contamination on the probe. Af- ter having removed the source of the false signals, the false signal suppres- sion must be deleted. Carry out a new false signal suppression |
| Measured value remains reproducible in one position during emptying | Stored false signals in this position are larger than the level echo | Delete false signal suppression Carry out a new false signal suppression |

Reaction after fault rectification

Depending on the reason for the fault and the measures taken, the steps described in chapter "*Setup*" must be carried out again or must be checked for plausibility and completeness.

9.5 Exchanging the electronics module

If the electronics module is defective, it can be replaced by the user.



In Ex applications, only instruments and electronics modules with appropriate Ex approval may be used.

If there is no electronics module available on site, the electronics module can be ordered through the agency serving you. The electronics modules are adapted to the respective sensor and differ in signal output or voltage supply.

The new electronics module must be loaded with the default settings of the sensor. These are the options:

- In the factory
- Or on site by the user

In both cases, the serial number of the sensor is needed. The serial numbers are stated on the type label of the instrument, on the inside of the housing as well as on the delivery note.

When loading on site, the order data must first be downloaded from the Internet (see operating instructions "*Electronics module*").



Caution:

All application-specific settings must be entered again. That's why you have to carry out a fresh setup after exchanging the electronics.

If you saved the parameter settings during the first setup of the sensor, you can transfer them to the replacement electronics module. A fresh setup is then not necessary.

9.6 Exchange or shorten cable/rod

Exchanging the cable/rod The cable or rod (meas. part) of the probe can be shortened, if necessary. To loosen the rod or cable you need a fork spanner with spanner width 13.

- 1. Loosen the rod or cable by applying a fork spanner to the flat surfaces (SW 13), provide counterforce with another fork spanner (SW 13)
- 2. Unscrew the loosened rod or cable manually.
- 3. Place the enclosed new double washer onto the thread.



Caution:

Make sure that the two components of the double washer remain together.

- 4. Screw the new rod and the new cable manually to the thread on the process fitting.
- 5. Exert counterforce with the second fork spanner and tighten the measuring rod or cable on the flat surfaces with a torque of 20 Nm (15 lbf ft).

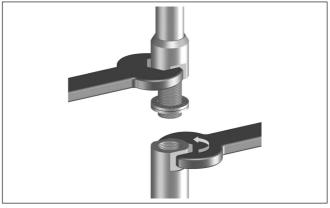


Fig. 31: Exchange cable or rod

Information:

Please maintain the specified torgue so that the max. tensile strength of the connection remains.

6. Enter new probe length and if necessary the new probe type and then carry out a fresh adjustment (see "Setup procedure, Carrying out min. adjustment - Carrying out max. adjustment").

Shorten cable/rod

The rod or cable of the probe can be shortened individually.

- 1. Mark the requested length with mounted measuring rod.
- 2. Cable: Loosen the pins on the gravity weight (hexagon 3)
- 3. Cable: remove the pins
- 4. Cable: Pull the cable out of the gravity weight

- 5. Shorten the cable/rod with a cut-off wheel or metal saw at the marking. Take note of the specifications in the following illustration when shortening the cable.
- 6. Cable with gravity weight: Shift the cable according to the drawing into the gravity weight
- 7. Cable with gravity weight: Fasten cable with the pins, torque 7 Nm (5.16 lbf ft)

Cable with centering weight: Fasten cable with the pins, torque 7 Nm (5.16 lbf ft) and fix the clamping part on the centering weight.

 Enter new probe length and then carry out a fresh adjustment (see "Setup procedure, Carrying out min. adjustment - Carrying out max. adjustment").

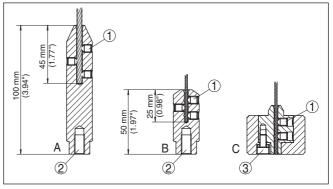


Fig. 32: Shortening the cable probe

- A Gravity weight cable ø 4 mm
- B Gravity weight cable ø 2 mm
- C Centering weight cable ø 2 mm
- 1 Threaded pins
- 2 Thread M8 for eye-bolt
- 3 Fixing screw centering weight

9.7 Software update

The following components are required to update the sensor software:

- Sensor
- Voltage supply
- PC with PACTware
- Current sensor software as file

You can find the actual sensor software as well as detailed information of the procedure in the download area on our homepage: www.siemens.com/sitranslg.

You can find information about the installation in the download file.



Caution:

Instruments with approvals can be bound to certain software versions. Therefore make sure that the approval is still effective after a software update is carried out.

You can find detailed information in the download area on our homepage: <u>www.siemens.com/sitranslg</u>.

9.8 How to proceed if a repair is necessary

If it is necessary to repair the instrument, please contact Siemens. You find the locations on "www.siemens.com/processautomation".

10 Dismount

Warning:

10.1 Dismounting steps



Before dismounting, be aware of dangerous process conditions such as e.g. pressure in the vessel or pipeline, high temperatures, corrosive or toxic media etc.

Take note of chapters "*Mounting*" and "*Connecting to voltage supply*" and carry out the listed steps in reverse order.

10.2 Disposal

The instrument consists of materials which can be recycled by specialised recycling companies. We use recyclable materials and have designed the electronics to be easily separable.

WEEE directive

The instrument does not fall in the scope of the EU WEEE directive. Article 2 of this Directive exempts electrical and electronic equipment from this requirement if it is part of another instrument that does not fall in the scope of the Directive. These include stationary industrial plants.

Pass the instrument directly on to a specialised recycling company and do not use the municipal collecting points.

If you have no way to dispose of the old instrument properly, please contact us concerning return and disposal.

11 Supplement

11.1 Technical data

General data

| .4435 |
|---------------------------------------------------------------------|
| |
| |
| 316L and PEEK GF30, Alloy C22 (2.4602) and PEEK GF30, 904L (1.4539) |
| 316L and PEEK GF30 |
| 316L or Alloy C22 (2.4602) |
| 316 (1.4401) |
| 316 (1.4401) |
| 316L |
| FFKM (Kalrez 6375) |
| On site (instruments with thread: Klingersil C-4400 is enclosed) |
| |
| Plastic PBT (Polyester) |
| Aluminium die-casting AlSi10Mg, powder-coated (Basis: Polyester) |
| 316L |
| 316L |
| Borosilicate glass GPC 540 |
| Silicone SI 850 R |
| Plastic housing: Polycarbonate Metal housing: Glass |
| 316L |
| PA, stainless steel, brass |
| NBR |
| PA |
| |
| |
| 316L |
| Borosilicate glass GPC 540 |
| Alloy C22 (2.4602) |
| |

| Helium leak rate | < 10 ⁻⁶ mbar l/s |
|--------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| Pressure resistance | See process pressure of the sensor |
| Process fittings | |
| Pipe thread, cylindrical (ISO 228 T1) | G¾, G1, G1½ (DIN 3852-A) |
| - Pipe thread, conical (ASME B1.20.1) | 34 NPT, 1 NPT, 11⁄2 NPT |
| - Flanges | DIN from DN 25, ASME from 1" |
| Weight | |
| Instrument weight (depending on process fitting) | approx. 0.8 8 kg (0.176 17.64 lbs) |
| – Rod: ø 8 mm (0.315 in) | approx. 400 g/m (4.31 oz/ft) |
| – Cable: ø 2 mm (0.079 in) | approx. 20 g/m (0.22 oz/ft) |
| – Cable: ø 4 mm (0.157 in) | approx. 80 g/m (0.86 oz/ft) |
| Gravity weight | approx. 325 g (11.5 oz) |
| Probe length L (from seal surface) | |
| – Rod: ø 8 mm (0.315 in) | up to 4 m (13.12 ft) |
| Trimming accuracy (rod) | ±(2 mm + 0.05 % of the rod length) |
| – Cable: ø 2 mm (0.079 in) | up to 32 m (105 ft) |
| – Cable: ø 4 mm (0.157 in) | up to 32 m (105 ft) |
| Trimming accuracy (cable) | ±(2 mm + 0.05 % of the cable length) |
| Lateral load | |
| – Rod: ø 8 mm (0.315 in) | 4 Nm (3 lbf ft) |
| Max. tensile load with cable: ø 2 mm (0.079 in) | 1.5 KN (337 lbf) |
| Max. tensile load with cable: ø 4 mm (0.157 in) | 2.5 KN (562 lbf) |
| Thread in gravity weight (cable version) | M 12 |
| Input variable | |
| Measured variable | Level of liquids |
| Min. dielectric constant of the medium - rod, cable version | ε _r > 1.7 |
| Output variable | |
| Output signal | 4 20 mA/HART |
| Range of the output signal | 3.8 20.5 mA/HART (default setting) |
| Fulfilled HART specification | 7 |
| Signal resolution | 0.3 μΑ |
| Fault signal, current output (adjustable) | Last valid measured value, \geq 21.0 mA, \leq 3.6 mA |
| | In order to detect the rarely occurring hardware failures in the device, we recommend monitoring both interfer- |

Max. output current

21.5 mA

ence values (\geq 21.0 mA, \leq 3.6 mA)

| Starting current | | |
|------------------------------------------------------------------------|------------------------------------|--|
| for 5 ms after switching on | ≤ 10 mA | |
| for run-up time | ≤ 3.6 mA | |
| Load | see load under Power supply | |
| Damping (63 % of the input variable), adjustable | 0 999 s | |
| HART output values according to HART 7 (default setting) ¹⁾ | | |
| First HART value (PV) | Linearised percentage value, level | |
| Second HART value (SV) | Distance to the level | |
| Third HART value (TV) | Measurement reliability, level | |
| Fourth HART value (QV) | Electronics temperature | |
| Indication value - Display and adjustment module ²⁾ | | |
| Displayed value 1 | Filling height Level | |
| Displayed value 2 | Electronics temperature | |
| Resolution, digital | < 1 mm (0.039 in) | |

Output variable - Additional current output

| For details on the operating voltage see chapter "Voltage supply" | | | |
|-------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| Output signal | 4 20 mA (passive) | | |
| Range of the output signal | 3.8 20.5 mA (default setting) | | |
| Signal resolution | 0.3 μΑ | | |
| Fault signal, current output (adjustable) | Last valid measured value, \geq 21.0 mA, \leq 3.6 mA | | |
| | In order to detect the rarely occurring hardware failures in the device, we recommend monitoring both interfer- ence values (\geq 21.0 mA, \leq 3.6 mA) | | |
| Max. output current | 21.5 mA | | |
| Starting current | | | |
| for 20 ms after switching on | ≤ 10 mA | | |
| for run-up time | ≤ 3.6 mA | | |
| Load | Load resistor, see chapter "Voltage supply" | | |
| Damping (63 % of the input variable), adjustable | 0 999 s | | |
| Indication value - Display and adjustment module ³⁾ | | | |
| Displayed value 1 | Filling height Level | | |
| Displayed value 2 | Electronics temperature | | |
| Resolution, digital | < 1 mm (0.039 in) | | |
| | | | |

¹⁾ The output values can be assigned individually.

²⁾ The indication values can be assigned individually.
 ³⁾ The indication values can be assigned individually.

Measurement accuracy (according to DIN EN 60770-1)

Process reference conditions according to DIN EN 61298-1

- Temperature
- Relative humidity
- Air pressure

Mounting, reference conditions

- Min. distance to internal installations
- Vessel

- Medium

- Mounting

> 500 mm (19.69 in)

(+12.5 ... +15.4 psig)

+18 ... +30 °C (+64 ... +86 °F)

+860 ... +1060 mbar/+86 ... +106 kPa

45 ... 75 %

metallic, ø 1 m (3.281 ft), centric mounting, process fitting flush with the vessel ceiling

Water/Oil (dielectric constant ~2.0)4)

Probe end does not touch the vessel bottom

Sensor parameter adjustment

No gating out of false signals carried out

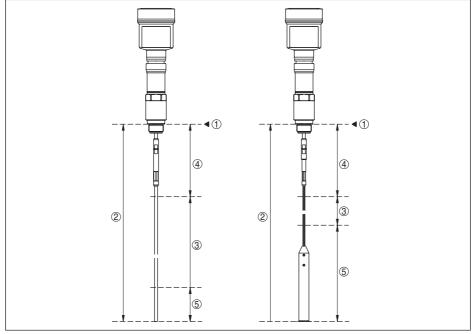


Fig. 33: Measuring ranges - SITRANS LG270

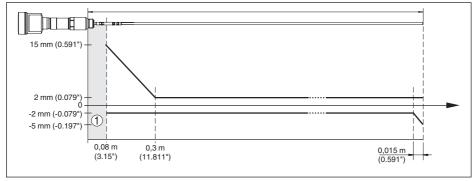
- 1 Reference plane
- 2 Probe length
- 3 Measuring range (default setting refers to the measuring range in water)
- 4 Upper dead zone (see following diagrams grey section)
- 5 Lower dead zone (see following diagrams grey section)

Typical deviation - Interface measure- ± 5 mm (0.197 in) ment

⁴⁾ With interface measurement = 2.0

49915-EN-200212

Typical deviation - Total level interface See following diagrams measurement



Typical deviation - Level measurement⁵⁾⁶⁾ See following diagrams



- 1 Dead zone (no measurement possible in this area)
- L Probe length

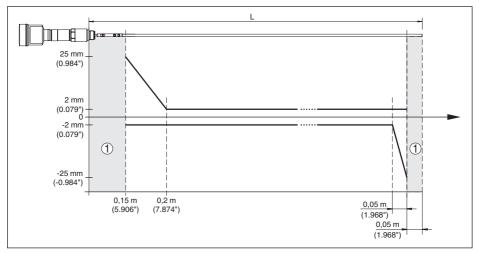


Fig. 35: Deviation SITRANS LG270 in rod version in oil

- 1 Dead zone (no measurement possible in this area)
- L Probe length



⁵⁾ Depending on the mounting conditions, deviations can occur which can be rectified by adapting the adjustment or changing the measured value offset in the DTM service mode

⁶⁾ The dead zones can be optimized via a false signal suppression.

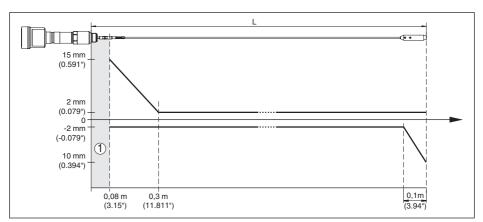


Fig. 36: Deviation SITRANS LG270 in cable version in water

- 1 Dead zone (no measurement possible in this area) When using a centering weight, it is only possible to measure up to the upper edge of the cerntering weight.
- L Probe length

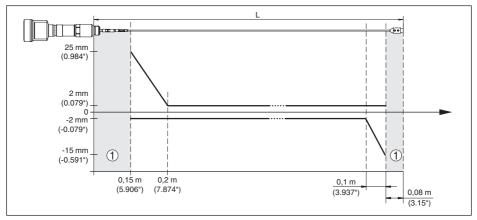


Fig. 37: Deviation SITRANS LG270 in cable version (2 mm/0.079 in), in medium oil

Dead zone (no measurement possible in this area) 1 When using a centering weight, it is only possible to measure up to the upper edge of the cerntering weight.

L Probe length

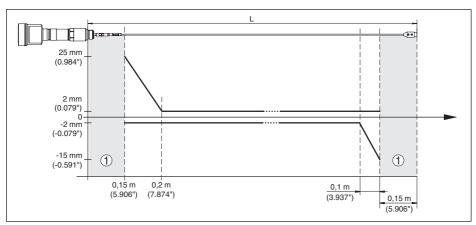


Fig. 38: Deviation SITRANS LG270 in cable version (4 mm/0.157 in), in medium oil

- 1 Dead zone (no measurement possible in this area)
- When using a centering weight, it is only possible to measure up to the upper edge of the cerntering weight. L Probe length

Non-repeatability

≤ ±1 mm

Variables influencing measurement accuracy

Specifications for the digital measured value

Temperature drift - Digital output ±3 mm/10 K relating to the max. measuring range or max. 10 mm (0.394 in)

Additional deviation through electromag- $< \pm 10$ mm ($< \pm 0.394$ in)

netic interference acc. to EN 61326

Specifications apply also to the current output⁷)

Temperature drift - Current output ±0.03 %/10 K relating to the 16 mA span or max. ±0.3 %

Deviation in the current output due to digital/analogue conversion

| Non-Ex and Ex-ia version | < ±15 μA |
|----------------------------------------------|----------|
|----------------------------------------------|----------|

Ex-d-ia version
 < ±40 μA

Additional deviation through electromag- $< \pm 150 \,\mu$ A

netic interference acc. to EN 61326

Influence of the superimposed gas and pressure on measurement accuracy

The propagation speed of the radar impulses in gas or vapour above the medium is reduced by high pressure. This effect depends on the superimposed gas or vapours.

The following table shows the resulting deviation for some typical gases and vapours. The specified values refer to the distance. Positive values mean that the measured distance is too large, negative values that the measured distance is too small.

⁷⁾ Also for the additional current output (optional).

| Gas phase | Temperature | Pressure | | | | | |
|-----------------------------------------------------------------|-----------------------------------------------------------|----------------------|---------------------------------------------------|------------------------------------------------------------|---------------------------------|------------------------|--|
| | | 10 bar (145 psig) | 50 bar (725 psig) | 100 bar (1450 psig) | 200 bar (2900 psig) | 400 bar (5800 psig) | |
| Air | 20 °C/68 °F | 0.22 % | 1.2 % | 2.4 % | 4.9 % | 9.5 % | |
| | 200 °C/392 °F | 0.13 % | 0.74 % | 1.5 % | 3 % | 6 % | |
| | 400 °C/752 °F | 0.08 % | 0.52 % | 1.1 % | 2.1 % | 4.2 % | |
| Hydrogen | 20 °C/68 °F | 0.10 % | 0.61 % | 1.2 % | 2.5 % | 4.9 % | |
| | 200 °C/392 °F | 0.05 % | 0.37 % | 0.76 % | 1.6 % | 3.1 % | |
| | 400 °C/752 °F | 0.03 % | 0.25 % | 0.53 % | 1.1 % | 2.2 % | |
| Steam (satu- | 100 °C/212 °F | - | - | - | - | - | |
| rated steam) | 180 °C/356 °F | 2.1 % | - | - | - | - | |
| | 264 °C/507 °F | 1.44 % | 9.2 % | - | - | - | |
| | 366 °C/691 °F | 1.01 % | 5.7 % | 13.2 % | 76 % | - | |
| | | | | | | | |
| | tics and perfor | rmance data | | | | | |
| Measuring cy | | | < 500 ms | | | | |
| Step response time ⁸⁾ | | | ≤3 s 1 m/min | | | | |
| Max. filling/er | nptying speed | | 1 m/min | | | | |
| | | | Products with min. | n high dielectric | constant (>10 |)) up to 5 m/ | |
| Ambient cor | nditions | | | | | | |
| Ambient, stor | age and transp | ort temperat | ure | | | | |
| Standard | | | -40 +80 °C | C (-40 +176 | °F) | | |
| - CSA, Ordi | nary Location | | -40 +60 °C (-40 +140 °F) | | | | |
| Process cor | ditions | | | | | | |
| For the proce | ss conditions, | olease also r | note the specifi | cations on the | type label. The | lowest value | |
| | IS. | | | | | | |
| always applie The measure | ment error thro | ugh the proc | ess conditions | in the specified | d pressure and | l temperature | |
| always applie The measure range is < 1 % Vessel pressi | ment error thro %. ure relating to tl | | see supplem | in the specified entary instructi <i>N-EN-ASME-J</i> | ons manual "F | | |
| always applie The measure range is < 1 % | ment error thro %. ure relating to tl sure stage | | see supplem <i>cording to DI</i> -1 +100 ba | entary instructi | ons manual "F IS")00 kPa | langes ac- | |

⁶⁾ Time span after a sudden measuring distance change by max. 0.5 m in liquid applications, max 2 m with bulk solids applications, until the output signal has taken for the first time 90 % of the final value (IEC 61298-2).

The measurement error from the process conditions is in the specified pressure and temperature range of below

1 %.

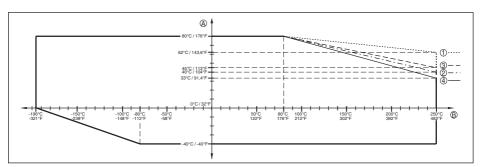


Fig. 39: Ambient temperature - process temperature, standard version

- A Ambient temperature
- B Process temperature (depending on the seal material)
- 1 Aluminium housing
- 2 Plastic housing
- 3 Stainless steel housing, precision casting
- 4 Stainless steel housing, electropolished

Flanges of 904L (1.4539): see ASME B16.5-2013, Table 2-3.11, permissible temperature range: -60 \dots +400 °C (-76 \dots 752 °F)

1 g with 5 ... 200 Hz according EN 60068-2-6 (vibration at resonance) with rod length 50 cm (19.69 in)

Vibration resistance

- Rod probe

Shock resistance

- Rod probe

25 g, 6 ms according to EN 60068-2-27 (mechanical shock) with rod length 50 cm (19.69 in)

Electromechanical data - version IP66/IP67 and IP66/IP68 (0.2 bar)

| Options | of | the | cable | entry |
|---------|----|-----|-------|-------|
|---------|----|-----|-------|-------|

- Cable entry
- Cable gland
 Blind plug

M20 x 1.5; 1/2 NPT M20 x 1.5; 1/2 NPT (cable ø see below table)

- M20 x 1.5: ½ NPT
- Closing cap

| Material ca- | Material seal | | С | able diameter | | |
|--------------------------|---------------|------------|--------|---------------|---------|----------|
| ble gland insert | | 4.5 8.5 mm | 5 9 mm | 6 12 mm | 7 12 mm | 10 14 mm |
| PA | NBR | - | • | • | - | • |
| Brass, nickel- plated | NBR | • | • | • | - | - |
| Stainless steel | NBR | - | • | • | _ | • |

1/2 NPT

Wire cross-section (spring-loaded terminals)

- Massive wire, stranded wire
- Stranded wire with end sleeve
- 0.2 ... 2.5 mm² (AWG 24 ... 14)
- 0.2 ... 1.5 mm² (AWG 24 ... 16)

| Electromechanical data - version IP66/IP68 (1 bar) | | | | | |
|------------------------------------------------------------------------|---------------------------------------------------------------|--|--|--|--|
| Options of the cable entry | Options of the cable entry | | | | |
| Cable gland with integrated connec- tion cable | M20 x 1.5 (cable diameter 5 9 mm) | | | | |
| Cable entry | 1/2 NPT | | | | |
| Blind plug | M20 x 1.5; ½ NPT | | | | |
| Connection cable | | | | | |
| - Configuration | four wires, one suspension cable, braiding, metal foil, cover | | | | |
| Wire cross-section | 0.5 mm² (AWG 20) | | | | |
| Wire resistance | < 0.036 Ω/m | | | | |
| Tensile strength | < 1200 N (270 lbf) | | | | |
| Standard length | 5 m (16.4 ft) | | | | |
| Max. length | 180 m (590.6 ft) | | | | |
| Min. bending radius (at 25 °C/77 °F) | 25 mm (0.984 in) | | | | |
| - Diameter | approx. 8 mm (0.315 in) | | | | |
| Colour - Non-Ex version | Black | | | | |
| - Colour - Ex-version | Blue | | | | |

| Display and adjustment module | | | |
|--------------------------------------------------------|------------------------------|--|--|
| Display element | Display with backlight | | |
| Measured value indication | | | |
| Number of digits | 5 | | |
| Adjustment elements | | | |
| – 4 keys | [OK], [->], [+], [ESC] | | |
| Protection rating | | | |
| - unassembled | IP 20 | | |
| Mounted in the housing without lid | IP 40 | | |
| Materials | | | |
| - Housing | ABS | | |
| Inspection window | Polyester foil | | |
| Functional safety | SIL non-reactive | | |
| Integrated clock | | | |
| Date format | Day.Month.Year | | |
| Time format | 12 h/24 h | | |
| Time zone, factory setting | CET | | |
| Max. rate deviation | 10.5 min/year | | |
| Additional output parameter - Electronics temperature | | | |
| Range | -40 … +85 °C (-40 … +185 °F) | | |
| Resolution | < 0.1 K | | |
| | | | |
| | | | |

| Deviation | ±3 K |
|------------------------------------------------------------|----------------------------------------------|
| Output of the temperature values | |
| - Indication | Via the display and adjustment module |
| - Output | Via the respective output signal |
| Voltage supply | |
| Operating voltage U _B | 9.6 35 V DC |
| Operating voltage $U_{\rm B}$ with lighting switched on | 16 35 V DC |
| Reverse voltage protection | Integrated |
| Permissible residual ripple | |
| - for 9.6 V < U _B < 14 V | ≤ 0.7 V _{eff} (16 … 400 Hz) |
| - for 18 V < U _B < 36 V | ≤ 1 V _{eff} (16 … 400 Hz) |
| Load resistor | |
| - Calculation | (U _B - U _{min})/0.022 A |
| Example - with U_B = 24 V DC | (24 V - 9.6 V)/0.022 A = 655 Ω |

| Potential connections and electrical separating measures in the instrument | | |
|----------------------------------------------------------------------------|------------------------------------------------------|--|
| Electronics | Not non-floating | |
| Reference voltage9) | 500 V AC | |
| Conductive connection | Between ground terminal and metallic process fitting | |

Electrical protective measures

| Housing material | Version | Protection acc. to IEC 60529 | Protection acc. to NEMA |
|-----------------------------------------|----------------|------------------------------------------|-------------------------|
| Plastic | Single chamber | IP66/IP67 | Type 4X |
| | Double chamber | IP66/IP67 | Type 4X |
| Aluminium | Single chamber | IP66/IP68 (0.2 bar) IP66/IP68 (1 bar) | Type 6P - |
| | Double chamber | IP66/IP68 (0.2 bar) IP66/IP68 (1 bar) | Type 6P - |
| Stainless steel (electro-pol- ished) | Single chamber | IP66/IP68 (0.2 bar) | Туре 6Р |
| Stainless steel (precision casting) | Single chamber | IP66/IP68 (0.2 bar) IP66/IP68 (1 bar) | Type 6P - |
| | Double chamber | IP66/IP68 (0.2 bar) IP66/IP68 (1 bar) | Type 6P - |

Connection of the feeding power supply Networks of overvoltage category III unit

⁹⁾ Galvanic separation between electronics and metal housing parts

Altitude above sea level

by default up to 2000 m (6562 ft)
 with connected overvoltage protection up to 5000 m (16404 ft)
 Pollution degree (with fulfilled housing protection)

Protection rating (IEC 61010-1) III

11.2 Dimensions

Plastic housing

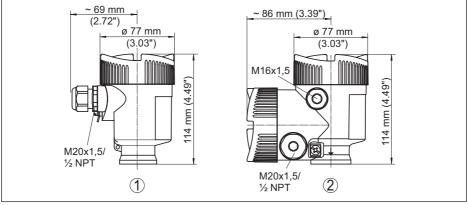


Fig. 40: Housing versions in protection IP66/IP67 (with integrated display and adjustment module the housing is 9 mm/0.35 in higher)

- 1 Plastic single chamber
- 2 Plastic double chamber

Aluminium housing

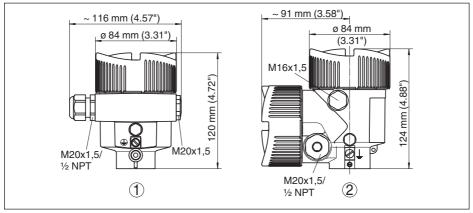


Fig. 41: Housing versions with protection rating IP66/IP68 (0.2 bar), (with integrated display and adjustment module the housing is 9 mm/0.35 in higher)

- 1 Aluminium single chamber
- 2 Aluminium double chamber

Stainless steel housing

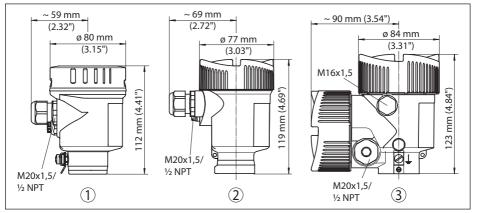
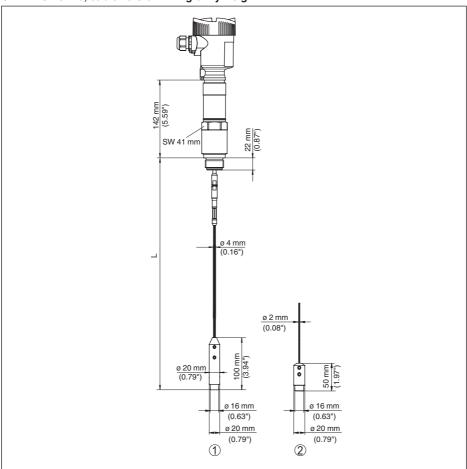


Fig. 42: Housing versions with protection rating IP66/IP68 (0.2 bar), (with integrated display and adjustment module the housing is 9 mm/0.35 in higher)

- 1 Stainless steel single chamber (electropolished)
- 2 Stainless steel single chamber (precision casting)
- 3 Stainless steel double chamber housing (precision casting)



SITRANS LG270, cable version with gravity weight

Fig. 43: SITRANS LG270, threaded version with gravity weight (all gravity weights with thread M8 for eye-bolt)

- L Sensor length, see chapter "Technical data"
- 1 Cable ø 4 mm (0.157 in)
- 2 Cable ø 2 mm (0.079 in)
- 3 Max. height of the vessel insulation

SITRANS LG270, cable version with centering weight

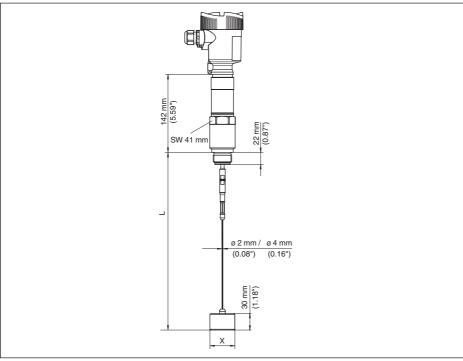


Fig. 44: SITRANS LG270, threaded version with centering weight

L Sensor length, see chapter "Technical data"

x ø 40 mm (1.57 in) ø 45 mm (1.77 in) ø 75 mm (2.95 in) ø 95 mm (3.74 in) (see supplementary instructions manual "Centering")

1 Max. height of the vessel insulation

SITRANS LG270, rod version

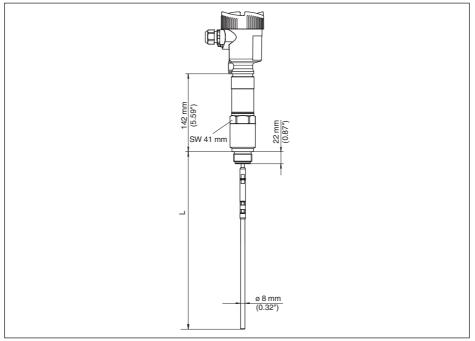


Fig. 45: SITRANS LG270, threaded version

- Sensor length, see chapter "Technical data" Max. height of the vessel insulation L
- 1

11.3 Trademark

All the brands as well as trade and company names used are property of their lawful proprietor/ originator.

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